



Pre-Hausdorff and Hausdorff Proximity Spaces

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Abstract. In this paper, an explicit characterization of the separation properties for T_0 , T_1 , $PreT_2$ (pre-Hausdorff) and T_2 (Hausdorff) is given in the topological category of proximity spaces. Moreover, specific relationships that arise among the various T_i , $i = 0, 1, 2$ and $PreT_2$ structures are examined in this category. Finally, we investigate the relationships among generalized separation properties for T_i , $i = 0, 1, 2$ and $PreT_2$ (in our sense), separation properties at a point p and separation properties for T_i , $i = 0, 1, 2$ in the usual sense in this category.

1. Introduction

The notion of proximity on a set X was introduced by Efremovich [17]. But the germ of the theory of proximity spaces, which have today become the basic concepts of the theory, was emerged by Frigyes Riesz [30] at the mathematical congress in Roma in 1908. This theory was axiomatized by Efremovich [17], [18] in 1934, but not published until 1951. He characterized the proximity relation “ A is close to B ” as a binary relation on subsets of a set X . In the interim, in 1941, a study was made by Wallace [35], [36] regarding “separation of sets”. This study can be considered as the primitive version of the same concept. Similar but weaker axioms than Efremovich’s were used.

Efremovich [18] defined the closure of a subset A of X to be the collection of all points of X “close” A . Thereby he showed that a topology (completely regular) can be introduced in a proximity space. He also showed that every completely regular space X can be turned into a proximity space by using Urysohn’s function. Efremovich later used proximity neighborhoods to obtain an equivalent set of axioms for a proximity space.

Much of the early work in proximity spaces was done by Smirnov [33] and [34]. He showed which topological spaces admit a proximity relation compatible with the given topology [34]. Smirnov was also the first to discover relationship between proximities and uniformities.

All our preliminary information on proximity spaces as well as additional information can be found in [28].

Various generalizations of the usual separation properties of topology and for an arbitrary topological category over sets separation properties at a point p are given in [2]. Baran [2] defined separation properties first at a point p , i.e., locally (see [3], [5], [10], [14], [23] and [24]), then they are generalized to point free

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definitions by using the generic element, [22] p. 39, method of topos theory. These generalizations are, for example, two notions of T_0 denoted by \bar{T}_0 and T'_0 , each equivalent to the classical T_0 notion for topological spaces, and two notions of $PreT_2$ denoted by $Pre\bar{T}_2$ and $PreT'_2$, each equivalent to the classical $PreT_2$ notion (for each distinct pair x and y in X , if the set $\{x, y\}$ is not indiscrete, then there exist disjoint neighborhoods of x and y) for topological spaces.

The main goal of this paper is

1. to give the characterization of the separation properties for T_0 , T_1 , $PreT_2$ and T_2 in the topological category of proximity spaces,
2. to examine how these generalizations are related, and
3. to show that the relationships among generalized separation properties for T_i , $i = 0, 1, 2$ and $PreT_2$ (in our sense), separation properties at a point p and separation properties for T_i , $i = 0, 1, 2$ in the usual sense in this category.

2. Preliminaries

The following are some basic definitions and notations which we will use throughout the paper.

Let \mathcal{E} and \mathcal{B} be any categories. The functor $\mathcal{U} : \mathcal{E} \rightarrow \mathcal{B}$ is said to be topological or that \mathcal{E} is a topological category over \mathcal{B} , if \mathcal{U} is concrete (i.e., faithful and amnestic), has small fibers, and for which every \mathcal{U} -source has an initial lift or, equivalently, for which each \mathcal{U} -sink has a final lift [1].

Note that a topological functor $\mathcal{U} : \mathcal{E} \rightarrow \mathcal{B}$ is said to be normalized, if constant objects, i.e., subterminals, have a unique structure [1, 5, 13, 27, 29].

Recall in [1] or [29], that an object $X \in \mathcal{E}$ (where $X \in \mathcal{E}$ stands for $X \in \text{Ob}(\mathcal{E})$), a topological category, is discrete iff every map $\mathcal{U}(X) \rightarrow \mathcal{U}(Y)$ lifts to a map $X \rightarrow Y$ for each object $Y \in \mathcal{E}$ and an object $X \in \mathcal{E}$ is indiscrete iff every map $\mathcal{U}(Y) \rightarrow \mathcal{U}(X)$ lifts to a map $Y \rightarrow X$ for each object $Y \in \mathcal{E}$.

Let \mathcal{E} be a topological category and $X \in \mathcal{E}$. A is called a subspace of X if the inclusion map $i : A \rightarrow X$ is an initial lift (i.e., an embedding) and we denote it by $A \subset X$.

Definition 2.1. [28] An Efremovich proximity (EF-proximity) space is a pair (X, δ) , where X is a set and δ is a binary relation on the power set of X such that

- (P1) $A \delta B$ iff $B \delta A$;
- (P2) $A \delta (B \cup C)$ iff $A \delta B$ or $A \delta C$;
- (P3) $A \delta B$ implies $A, B \neq \emptyset$;
- (P4) $A \cap B \neq \emptyset$ implies $A \delta B$;
- (P5) $A \not\delta B$ implies there is an $E \subseteq X$ such that $A \not\delta E$ and $(X - E) \not\delta B$;

where $A \not\delta B$ means it is not true that $A \delta B$.

A function $f : (X, \delta) \rightarrow (Y, \delta')$ between two proximity spaces is called a proximity mapping (or a p-map) iff $f(A) \delta' f(B)$ whenever $A \delta B$. It can easily be shown that f is a p-map iff, for subsets C and D of Y , $f^{-1}(C) \not\delta f^{-1}(D)$ whenever $C \not\delta' D$.

We denote the category of proximity spaces and proximity mappings by **Prox**. Hunsaker and Sharma [21] showed that the functor $\mathcal{U} : \mathbf{Prox} \rightarrow \mathbf{Set}$ is topological.

Definition 2.2. [31] Let X be a nonempty set and $P(X)$ be the set of all subsets of X . A proximity-base on X is a binary relation \mathfrak{B} on $P(X)$ satisfying the axioms (B1) through (B5) given below:

- (B1) $(\emptyset, X) \notin \mathfrak{B}$;
- (B2) $A \cap B \neq \emptyset$ implies $(A, B) \in \mathfrak{B}$;
- (B3) $(A, B) \in \mathfrak{B}$ iff $(B, A) \in \mathfrak{B}$;
- (B4) If $(A, B) \in \mathfrak{B}$ and $A \subseteq A^*$, $B \subseteq B^*$ then $(A^*, B^*) \in \mathfrak{B}$;
- (B5) If $(A, B) \notin \mathfrak{B}$ then there exists a set $E \subseteq X$ such that $(A, E) \notin \mathfrak{B}$ and $(X - E, B) \notin \mathfrak{B}$.

2.3 Let \mathfrak{B} be a proximity-base on a set X and let a binary relation δ on $P(X)$ be defined as follows: $(A, B) \in \delta$ if, given any finite covers $\{A_i : 1 \leq i \leq n\}$ and $\{B_j : 1 \leq j \leq m\}$ of A and B respectively, then there exists a pair (i, j) such that $(A_i, B_j) \in \mathfrak{B}$. δ is a proximity on X finer than the relation \mathfrak{B} [21] or [31].

2.4 Let X be a non-empty set, for each $i \in I$, (X_i, δ_i) be a proximity space and $f_i : X \rightarrow (X_i, \delta_i)$ be a source in **Prox**. Define a binary relation \mathfrak{B} on $P(X)$ as follows: for $A, B \in P(X)$, $A \mathfrak{B} B$ iff $f_i(A) \delta_i f_i(B)$, for all $i \in I$. \mathfrak{B} is a proximity-base on X (Theorem 3.8, [31]). The initial proximity structure δ on X generated by the proximity base \mathfrak{B} is given by for $A, B \in P(X)$, $A \delta B$ iff for any finite covers $\{A_i : 1 \leq i \leq n\}$ and $\{B_j : 1 \leq j \leq m\}$ of A and B respectively, then there exists a pair (i, j) such that $(A_i, B_j) \in \mathfrak{B}$ [31].

2.5 Let (X, δ) be a proximity space, Y a non-empty set and f a function from a proximity space (X, δ) onto a set Y . The quotient proximity δ^* on Y is defined as follows for every $A, B \subset Y$: $A \delta^* B$ iff, for each binary rational s in $[0, 1]$, there is some $C_s \subset Y$ such that $C_0 = A$, $C_1 = B$ and $s < t$ implies $f^{-1}(C_s) \delta f^{-1}(C_t)$ [20] or [38] p. 276.

2.6 We write Δ for the diagonal in X^2 , where $X \in \mathbf{Prox}$. For $X \in \mathbf{Prox}$ we define the wedge $X^2 \vee_{\Delta} X^2$, as the final structure, with respect to the map $X^2 \amalg X^2 \rightarrow X^2 \vee_{\Delta} X^2$, that is the identification of the two copies of X^2 along the diagonal Δ . An epi sink $\{i_1, i_2 : (X^2, \delta) \rightarrow (X^2 \vee_{\Delta} X^2, \delta')\}$, where i_1, i_2 are the canonical injections, in **Prox** is a final lift if and only if the following statement holds. For each pair A, B in the different component of $X^2 \vee_{\Delta} X^2$, $A \delta' B$ iff there exist sets C, D and U in X^2 such that $C \delta U$ and $U \delta D$ with $i_k^{-1}(A) = C$ and $i_j^{-1}(B) = D$ for $k, j = 1, 2$ and $k \neq j$. If A and B are in the same component of wedge, then $A \delta' B$ iff there exist sets C, D in X^2 such that $C \delta D$ and $i_k^{-1}(A) = C$ and $i_k^{-1}(B) = D$ for some $k = 1, 2$. Specially, if $i_k(E) = A$ and $i_k(F) = B$, then $(i_k(E), i_k(F)) \in \delta'$ iff $(i_k^{-1}(i_k(E)), i_k^{-1}(i_k(F))) = (E, F) \in \delta$. This is a special case of 2.5.

2.7 Let X be a non-empty set. The discrete proximity structure δ on X is defined as follows for $A, B \subset X$: $A \delta B$ iff $A \cap B \neq \emptyset$ [28] p. 9.

2.8 Let X be a non-empty set. The indiscrete proximity structure δ on X is defined as follows for $A, B \subset X$: $A \delta B$ iff $A \neq \emptyset$ and $B \neq \emptyset$ [19] p. 5.

3. $T_0, T_1, PreT_2$ and T_2 Proximity Spaces

Let B be a nonempty set, $B^2 = B \times B$ be cartesian product of B with itself and $B^2 \vee_{\Delta} B^2$ be two distinct copies of B^2 identified along the diagonal, i.e., the result of pushing out Δ along itself. A point (x, y) in $B^2 \vee_{\Delta} B^2$ will be denoted by $(x, y)_1((x, y)_2)$ if (x, y) is in the first (resp. second) component of $B^2 \vee_{\Delta} B^2$. Clearly $(x, y)_1 = (x, y)_2$ iff $x = y$ [2].

The principal axis map $A : B^2 \vee_{\Delta} B^2 \rightarrow B^3$ is given by $A(x, y)_1 = (x, y, x)$ and $A(x, y)_2 = (x, x, y)$. The skewed axis map $S : B^2 \vee_{\Delta} B^2 \rightarrow B^3$ is given by $S(x, y)_1 = (x, y, y)$ and $S(x, y)_2 = (x, x, y)$ and the fold map, $\nabla : B^2 \vee_{\Delta} B^2 \rightarrow B^2$ is given by $\nabla(x, y)_i = (x, y)$ for $i = 1, 2$. Note that $\pi_1 S = \pi_{11} = \pi_1 A$, $\pi_2 S = \pi_{21} = \pi_2 A$, $\pi_3 A = \pi_{12}$, and $\pi_3 S = \pi_{22}$, where $\pi_k : B^3 \rightarrow B$ the k -th projection $k = 1, 2, 3$ and $\pi_{ij} = \pi_i + \pi_j : B^2 \vee_{\Delta} B^2 \rightarrow B$, for $i, j \in \{1, 2\}$ [2].

Definition 3.1. (cf. [2] and [13]) Let $\mathcal{U} : \mathcal{E} \rightarrow \mathbf{Set}$ be a topological functor, X an object in \mathcal{E} with $\mathcal{U}(X) = B$.

1. X is \overline{T}_0 iff the initial lift of the \mathcal{U} -source $\{A : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(X^3) = B^3$ and $\nabla : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}\mathcal{D}(B^2) = B^2\}$ is discrete, where \mathcal{D} is the discrete functor which is a left adjoint to \mathcal{U} [2].
2. X is T'_0 iff the initial lift of the \mathcal{U} -source $\{id : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(B^2 \vee_{\Delta} B^2)' = B^2 \vee_{\Delta} B^2$ and $\nabla : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}\mathcal{D}(B^2) = B^2\}$ is discrete, where $(B^2 \vee_{\Delta} B^2)'$ is the final lift of the \mathcal{U} -sink $\{i_1, i_2 : \mathcal{U}(X^2) = B^2 \rightarrow B^2 \vee_{\Delta} B^2\}$, i_1 and i_2 are the canonical injections, and $\mathcal{D}(B^2)$ is the discrete structure on B^2 [2], [6].
3. X is T_1 iff the initial lift of the \mathcal{U} -source $\{S : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(X^3) = B^3$ and $\nabla : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}\mathcal{D}(B^2) = B^2\}$ is discrete [2].
4. X is $Pre\overline{T}_2$ iff the initial lift of the \mathcal{U} -sources $\{A : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(X^3) = B^3\}$ and $\{S : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(X^3) = B^3\}$ agree.
5. X is $PreT'_2$ iff the initial lift of the \mathcal{U} -source $\{S : B^2 \vee_{\Delta} B^2 \rightarrow \mathcal{U}(X^3) = B^3\}$ and the final lift of the \mathcal{U} -sink $\{i_1, i_2 : \mathcal{U}(X^2) = B^2 \rightarrow B^2 \vee_{\Delta} B^2\}$ agree.
6. X is \overline{T}_2 iff X is \overline{T}_0 and $Pre\overline{T}_2$.
7. X is T'_2 iff X is T'_0 and $PreT'_2$.

- Remark 3.2.** 1. Note that for the category **Top** of topological spaces, \bar{T}_0 , T'_0 or T_1 or $\text{Pre}\bar{T}_2$, $\text{Pre}T'_2$ or \bar{T}_2 , T'_2 reduce to usual T_0 or T_1 or $\text{Pre}T_2$ (for each distinct pair x and y in X , if the set $\{x, y\}$ is not indiscrete, then there exist disjoint neighborhoods of x and y) or T_2 separation axioms, respectively [2, 26, 37].
2. For an arbitrary topological category, we have \bar{T}_0 implies T'_0 ([6], Theorem 3.2) but the reverse implication is generally not true (see [6] or 3.3 and 3.4, below).
3. Let $\mathcal{U} : \mathcal{E} \rightarrow \mathbf{Set}$ be a topological functor, X an object in \mathcal{E} and $p \in \mathcal{U}(X)$ be a retract of X , i.e., the initial lift $h : 1 \rightarrow X$ of the \mathcal{U} -source $p : 1 \rightarrow \mathcal{U}(X)$ is a retract, where 1 is the terminal object in \mathbf{Set} . Then if X is \bar{T}_0 (resp. T_1), then X is \bar{T}_0 at p (resp. T_1 at p) but the reverse implication is not true, in general ([5], Theorem 2.6).
4. If $\mathcal{U} : \mathcal{E} \rightarrow \mathbf{Set}$ be a normalized topological functor, then \bar{T}_0 (resp. T_1) implies \bar{T}_0 at p (resp. T_1 at p) ([5], Corollary 2.9).

Theorem 3.3. An Efremovich proximity space (X, δ) is \bar{T}_0 if and only if, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.

Proof. Suppose that (X, δ) is \bar{T}_0 , i.e., 2.4, 2.7 and Definition 3.1, for any sets U, V on $X^2 \vee_{\Delta} X^2$, $\pi_{11}U \delta \pi_{11}V$, $\pi_{21}U \delta \pi_{21}V$, $\pi_{12}U \delta \pi_{12}V$ and $\nabla U \delta_d^2 \nabla V$ iff $U \cap V \neq \emptyset$ (δ_d^2 is the discrete proximity structure on X^2).

We shall show that the condition holds. Suppose for some $x, y \in X$, $(\{x\}, \{y\}) \in \delta$ with $x \neq y$. Then, by 2.4, 2.7 and Definition 3.1, for $(U, V) \in \delta'$ (δ' is an Efremovich proximity structure on $X^2 \vee_{\Delta} X^2$) with $U = \{(x, y)_1\}$ and $V = \{(x, y)_2\}$, $\pi_{11}U \delta \pi_{11}V = \pi_{1A}\{(x, y)_1\} \delta \pi_{1A}\{(x, y)_2\} = \pi_{1}\{(x, y, x)\} \delta \pi_{1}\{(x, x, y)\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{21}U \delta \pi_{21}V = \pi_{2A}\{(x, y)_1\} \delta \pi_{2A}\{(x, y)_2\} = \pi_{2}\{(x, y, x)\} \delta \pi_{2}\{(x, x, y)\} = \{y\} \delta \{x\}$, i.e., $(\{y\}, \{x\}) \in \delta$, $\pi_{12}U \delta \pi_{12}V = \pi_{3A}\{(x, y)_1\} \delta \pi_{3A}\{(x, y)_2\} = \pi_{3}\{(x, y, x)\} \delta \pi_{3}\{(x, x, y)\} = \{x\} \delta \{y\}$, i.e., $(\{x\}, \{y\}) \in \delta$, where $\pi_i : X^3 \rightarrow X$, $i = 1, 2, 3$, are the projection maps, and $\nabla\{(x, y)_1\} \delta_d^2 \nabla\{(x, y)_2\} = \{(x, y)\} \delta_d^2 \{(x, y)\}$, i.e., $(\{(x, y)\}, \{(x, y)\}) \in \delta_d^2$, (δ_d^2 is the discrete proximity structure on X^2). But $U \cap V = \emptyset$. This is a contradiction to the fact that (X, δ) is \bar{T}_0 . Hence if $(\{x\}, \{y\}) \in \delta$, then $x = y$.

Conversely, suppose that for each $x \neq y$, $(\{x\}, \{y\}) \notin \delta$. We need to show that (X, δ) is \bar{T}_0 , i.e., by 2.4, 2.7 and Definition 3.1, we must show that the proximity structure δ' on $X^2 \vee_{\Delta} X^2$ induced by $A : X^2 \vee_{\Delta} X^2 \rightarrow \mathcal{U}((X^3, \delta^3)) = X^3$ and $\nabla : X^2 \vee_{\Delta} X^2 \rightarrow \mathcal{U}((X^2, \delta_d^2)) = X^2$ is discrete, where δ^3 and δ_d^2 are the product proximity structure on X^3 and the discrete proximity structure on X^2 , respectively. Let (U, V) be any set in δ' , i.e., $\pi_i A(U) \delta \pi_i A(V)$ ($i = 1, 2, 3$) and $\nabla U \delta_d^2 \nabla V$.

Since δ_d^2 is the discrete proximity structure and $\nabla U \delta_d^2 \nabla V$, then $\nabla U \cap \nabla V \neq \emptyset$. It follows that there exists $(x, y) \in \nabla U \cap \nabla V$. Hence, there exist $t \in U$ and $z \in V$ such that $\nabla t = (x, y) = \nabla z$. If $x = y$, then $t = (x, y)_i = z$, ($i = 1, 2$) and $(x, y)_i \in U \cap V$.

If $x \neq y$, then $t = (x, y)_i$, $z = (x, y)_j$ ($i, j = 1, 2$). We need to show that $U \cap V \neq \emptyset$, i.e., U and V are in the first or in the second or in both component of $X^2 \vee_{\Delta} X^2$.

If U subset of the first component of $X^2 \vee_{\Delta} X^2$ and V subset of the second component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_1\} \subseteq U$ and $\{(x, y)_2\} \subseteq V$. It follows that $\pi_{3A}\{(x, y)_1\} \delta \pi_{3A}\{(x, y)_2\} = \pi_{3}\{(x, y, x)\} \delta \pi_{3}\{(x, x, y)\} = \{x\} \delta \{y\}$, i.e., $(\{x\}, \{y\}) \in \delta$. Since $(\{x\}, \{y\}) \notin \delta$ (by assumption), $(\{(x, y)_1\}, \{(x, y)_2\}) \notin \delta'$ by the condition (P2) of 2.1.

The case U subset of the second component of $X^2 \vee_{\Delta} X^2$ and V subset of the first component of $X^2 \vee_{\Delta} X^2$ can be handled similarly. Hence U and V can not be in different component of $X^2 \vee_{\Delta} X^2$.

If U and V are in both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U subset of the first component of $X^2 \vee_{\Delta} X^2$ and V subset of both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1\}$ and $V \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U subset of both component of $X^2 \vee_{\Delta} X^2$ and V subset of the second component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq \{(x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U and V are in the first component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1\}$ and $V \supseteq \{(x, y)_1\}$. Hence $U \cap V \neq \emptyset$. Similarly if U and V are in the second component of $X^2 \vee_{\Delta} X^2$, then $U \cap V \neq \emptyset$.

If $(\{(x, y)_i\}, \{(x, y)_i\}) \in \delta'$, ($i = 1, 2$), then $\pi_{1A}\{(x, y)_1\} \delta \pi_{1A}\{(x, y)_1\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{2A}\{(x, y)_1\} \delta \pi_{2A}\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, $\pi_{3A}\{(x, y)_1\} \delta \pi_{3A}\{(x, y)_1\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$ and $\pi_{1A}\{(x, y)_2\} \delta \pi_{1A}\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{2A}\{(x, y)_2\} \delta \pi_{2A}\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{3A}\{(x, y)_2\} \delta \pi_{3A}\{(x, y)_2\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$.

We must have $(U, V) \supseteq (\{(x, y)_i\}, \{(x, y)_i\})$, $(i = 1, 2)$, i.e., $U \cap V \neq \emptyset$ and consequently, by 2.4, 2.7 and Definition 3.1, (X, δ) is \overline{T}_0 . \square

Theorem 3.4. *An Efremovich proximity space is T'_0 .*

Proof. Let (X, δ) be any Efremovich proximity space. By 2.4, 2.6, 2.7 and Definition 3.1, we will show that for any $(i_k(E), i_k(F)) \in \delta'$ (δ' is an Efremovich proximity structure on $X^2 \vee_{\Delta} X^2$), if $i_k(E, F) = (i_k(E), i_k(F)) \in \delta'$ ($k = 1, 2$) for some $(E, F) \in \delta^2$ ($E, F \subset X^2$ and δ^2 is the product proximity structure on X^2) and $(\nabla(i_k(E)), \nabla(i_k(F))) \in \delta_d^2$ (δ_d^2 is the discrete proximity structure on X^2), then we will show that $(i_k(E), i_k(F)) \supseteq (\{(x, y)_k\}, \{(x, y)_k\})$, ($k = 1, 2$), i.e., $i_k(E) \cap i_k(F) \neq \emptyset$.

Since δ_d^2 is the discrete proximity structure and $\nabla(i_k(E)) \delta_d^2 \nabla(i_k(F))$, then $\nabla(i_k(E)) \cap \nabla(i_k(F)) \neq \emptyset$. It follows that there exists $(x, y) \in \nabla(i_k(E)) \cap \nabla(i_k(F))$. Hence, there exist $t \in i_k(E)$ and $z \in i_k(F)$ such that $\nabla t = (x, y) = \nabla z$. If $x = y$, then $t = (x, y)_k = z$, ($k = 1, 2$).

If $x \neq y$, then $t = (x, y)_k$, $z = (x, y)_n$ ($k, n = 1, 2$). We need to show that $i_k(E) \cap i_k(F) \neq \emptyset$, i.e., $i_k(E)$ and $i_k(F)$ are in the first or in the second or in both component of $X^2 \vee_{\Delta} X^2$.

If $i_k(E)$ subset of the first component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of the second component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_1\} \subseteq i_k(E)$ and $\{(x, y)_2\} \subseteq i_k(F)$. But, if $(i_k(E), i_k(F)) \supseteq (\{(x, y)_1\}, \{(x, y)_2\}) \in \delta'$ for some $(E, F) \in \delta^2$ and $k = 1$ (resp. $k = 2$), then $(\{(x, y)_1\}, \{(x, y)_2\}) \in (i_1(E), i_1(F))$ which shows that $(x, y)_2$ (resp. $(x, y)_1$) must be in the first (resp. second) component of $X^2 \vee_{\Delta} X^2$, a contradiction since $x \neq y$.

Similarly, if $i_k(E)$ subset of the second component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of the first component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_2\} \subseteq i_k(E)$ and $\{(x, y)_1\} \subseteq i_k(F)$. But, if $(i_k(E), i_k(F)) \supseteq (\{(x, y)_2\}, \{(x, y)_1\}) \in \delta'$ for some $(E, F) \in \delta^2$ and $k = 1$ (resp. $k = 2$), then $(\{(x, y)_2\}, \{(x, y)_1\}) \in (i_1(E), i_1(F))$ which shows that $(x, y)_2$ (resp. $(x, y)_1$) must be in the first (resp. second) component of $X^2 \vee_{\Delta} X^2$, a contradiction since $x \neq y$. Hence $i_k(E)$ and $i_k(F)$ can not be in different component of $X^2 \vee_{\Delta} X^2$.

If $i_k(E)$ and $i_k(F)$ are in both component of $X^2 \vee_{\Delta} X^2$, then $i_k(E) \supseteq \{(x, y)_1, (x, y)_2\}$ and $i_k(F) \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $i_k(E) \cap i_k(F) \neq \emptyset$.

If $i_k(E)$ subset of the first component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of both component of $X^2 \vee_{\Delta} X^2$, then $i_k(E) \supseteq \{(x, y)_1\}$ and $i_k(F) \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $i_k(E) \cap i_k(F) \neq \emptyset$.

If $i_k(E)$ subset of both component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of the second component of $X^2 \vee_{\Delta} X^2$, then $i_k(E) \supseteq \{(x, y)_1, (x, y)_2\}$ and $i_k(F) \supseteq \{(x, y)_2\}$. Hence $i_k(E) \cap i_k(F) \neq \emptyset$.

If $i_k(E)$ and $i_k(F)$ are in the first component of $X^2 \vee_{\Delta} X^2$, then $i_k(E) \supseteq \{(x, y)_1\}$ and $i_k(F) \supseteq \{(x, y)_1\}$. Hence $i_k(E) \cap i_k(F) \neq \emptyset$. Similarly if $i_k(E)$ and $i_k(F)$ are in the second component of $X^2 \vee_{\Delta} X^2$, then $i_k(E) \cap i_k(F) \neq \emptyset$.

We must have $(i_k(E), i_k(F)) \supseteq (\{(x, y)_i\}, \{(x, y)_i\})$, $(i = 1, 2)$, i.e., $i_k(E) \cap i_k(F) \neq \emptyset$ and consequently, by 2.4, 2.6, 2.7 and Definition 3.1, (X, δ) is T'_0 . \square

Theorem 3.5. *An Efremovich proximity space (X, δ) is T_1 if and only if, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.*

Proof. Suppose that (X, δ) is T_1 , i.e., 2.4, 2.7 and Definition 3.1, for any sets U, V on $X^2 \vee_{\Delta} X^2$, $\pi_{11}U \delta \pi_{11}V$, $\pi_{21}U \delta \pi_{21}V$, $\pi_{22}U \delta \pi_{22}V$ and $\nabla U \delta_d^2 \nabla V$ iff $U \cap V \neq \emptyset$ (δ_d^2 is the discrete proximity structure on X^2).

We shall show that the condition holds. Suppose for some $x, y \in X$, $(\{x\}, \{y\}) \in \delta$ with $x \neq y$. Then, by 2.4, 2.7 and Definition 3.1, for $(U, V) \in \delta'$ (δ' is an Efremovich proximity structure on $X^2 \vee_{\Delta} X^2$) with $U = \{(x, y)_1\}$ and $V = \{(x, y)_2\}$, $\pi_{11}U \delta \pi_{11}V = \pi_1 S \{(x, y)_1\} \delta \pi_1 S \{(x, y)_2\} = \pi_1 \{(x, y, y)\} \delta \pi_1 \{(x, x, y)\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{21}U \delta \pi_{21}V = \pi_2 S \{(x, y)_1\} \delta \pi_2 S \{(x, y)_2\} = \pi_2 \{(x, y, y)\} \delta \pi_2 \{(x, x, y)\} = \{y\} \delta \{x\}$, i.e., $(\{y\}, \{x\}) \in \delta$, $\pi_{22}U \delta \pi_{22}V = \pi_3 S \{(x, y)_1\} \delta \pi_3 S \{(x, y)_2\} = \pi_3 \{(x, y, y)\} \delta \pi_3 \{(x, x, y)\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, where $\pi_i : X^3 \rightarrow X$, $i = 1, 2, 3$, are the projection maps, and $\nabla \{(x, y)_1\} \delta_d^2 \nabla \{(x, y)_2\} = \{(x, y)\} \delta_d^2 \{(x, y)\}$, i.e., $(\{(x, y)\}, \{(x, y)\}) \in \delta_d^2$ (δ_d^2 is the discrete proximity structure on X^2). But $U \cap V = \emptyset$. This is a contradiction to the fact that (X, δ) is T_1 . Hence if $(\{x\}, \{y\}) \in \delta$, then $x = y$.

Conversely, suppose that for each $x \neq y$, $(\{x\}, \{y\}) \notin \delta$. We need to show that (X, δ) is T_1 , i.e., by 2.4, 2.7 and Definition 3.1, we must show that the proximity structure δ' on $X^2 \vee_{\Delta} X^2$ induced by $S : X^2 \vee_{\Delta} X^2 \rightarrow \mathcal{U}((X^3, \delta^3)) = X^3$ and $\nabla : X^2 \vee_{\Delta} X^2 \rightarrow \mathcal{U}((X^2, \delta_d^2)) = X^2$ is discrete, where δ^3 and δ_d^2 are the product proximity structure on X^3 and the discrete proximity structure on X^2 , respectively. Let (U, V) be any set in δ' , i.e., $\pi_i S(U) \delta \pi_i S(V)$ ($i = 1, 2, 3$) and $\nabla U \delta_d^2 \nabla V$.

Since δ_d^2 is the discrete proximity structure and $\nabla U \delta_d^2 \nabla V$, then $\nabla U \cap \nabla V \neq \emptyset$. It follows that there exists $(x, y) \in \nabla U \cap \nabla V$. Hence, there exist $t \in U$ and $z \in V$ such that $\nabla t = (x, y) = \nabla z$. If $x = y$, then $t = (x, y)_i = z$, ($i = 1, 2$) and $(x, y)_i \in U \cap V$.

If $x \neq y$, then $t = (x, y)_i, z = (x, y)_j$ ($i, j = 1, 2$). We need to show that $U \cap V \neq \emptyset$, i.e., U and V are in the first or in the second or in both component of $X^2 \vee_{\Delta} X^2$.

If U subset of the first component of $X^2 \vee_{\Delta} X^2$ and V subset of the second component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_1\} \in U$ and $\{(x, y)_2\} \in V$. It follows that $\pi_2 S\{(x, y)_1\} \delta \pi_2 S\{(x, y)_2\} = \pi_2\{(x, y, y)\} \delta \pi_2\{(x, x, y)\} = \{y\} \delta \{x\}$, i.e., $(\{y\}, \{x\}) \in \delta$. Since $(\{x\}, \{y\}) \notin \delta$ (by assumption), $(\{(x, y)_1\}, \{(x, y)_2\}) \notin \delta'$ by the condition (P2) of 2.1.

The case U subset of the second component of $X^2 \vee_{\Delta} X^2$ and V subset of the first component of $X^2 \vee_{\Delta} X^2$ can be handled similarly. Hence U and V can not be in different component of $X^2 \vee_{\Delta} X^2$.

If U and V are in both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U subset of the first component of $X^2 \vee_{\Delta} X^2$ and V subset of both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1\}$ and $V \supseteq \{(x, y)_1, (x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U subset of both component of $X^2 \vee_{\Delta} X^2$ and V subset of the second component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq \{(x, y)_2\}$. Hence $U \cap V \neq \emptyset$.

If U and V are in the first component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq \{(x, y)_1\}$ and $V \supseteq \{(x, y)_1\}$. Hence $U \cap V \neq \emptyset$. Similarly if U and V are in the second component of $X^2 \vee_{\Delta} X^2$, then $U \cap V \neq \emptyset$.

If $(\{(x, y)_i\}, \{(x, y)_i\}) \in \delta'$, ($i = 1, 2$), then $\pi_1 S\{(x, y)_1\} \delta \pi_1 S\{(x, y)_1\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2 S\{(x, y)_1\} \delta \pi_2 S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, $\pi_3 S\{(x, y)_1\} \delta \pi_3 S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$ and $\pi_1 S\{(x, y)_2\} \delta \pi_1 S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2 S\{(x, y)_2\} \delta \pi_2 S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_3 S\{(x, y)_2\} \delta \pi_3 S\{(x, y)_2\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$.

We must have $(U, V) \supseteq (\{(x, y)_i\}, \{(x, y)_i\})$, ($i = 1, 2$), i.e., $U \cap V \neq \emptyset$ and consequently, by 2.4, 2.7 and Definition 3.1, (X, δ) is T_1 . \square

Remark 3.6. Let (X, δ) be an Efremovich proximity space, it follows there are Theorems 3.3, 3.5 that (X, δ) is \bar{T}_0 if and only if (X, δ) is T_1 if and only if, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.

Theorem 3.7. An Efremovich proximity space is $Pre\bar{T}_2$.

Proof. Let (X, δ) be any Efremovich proximity space. We will show that (X, δ) is $Pre\bar{T}_2$, i.e., by 2.4 and Definition 3.1, for any pair U and V in the wedge, $\pi_1 A(U) \delta \pi_1 A(V)$, $\pi_2 A(U) \delta \pi_2 A(V)$ and $\pi_3 A(U) \delta \pi_3 A(V)$ iff $\pi_1 S(U) \delta \pi_1 S(V)$, $\pi_2 S(U) \delta \pi_2 S(V)$ and $\pi_3 S(U) \delta \pi_3 S(V)$, respectively.

We consider various possibilities for U and V ; namely $U \supseteq \{(x, y)_1\}, \{(x, y)_2\}$ or $\{(x, x)\}$ and $V \supseteq \{(z, w)_1\}, \{(z, w)_2\}$ or $\{(z, z)\}$ for some $x, y, z, w \in X$. By the condition (P2) of 2.1 it is sufficient to take "equality" instead of "superset" for the possibilities above.

If $U = \{(x, y)_1\}$ and $V = \{(z, w)_1\}$, then $\pi_1 A(U) \delta \pi_1 A(V) = \{x\} \delta \{z\} = \pi_1 S(U) \delta \pi_1 S(V)$, $\pi_2 A(U) \delta \pi_2 A(V) = \{y\} \delta \{w\} = \pi_2 S(U) \delta \pi_2 S(V)$, and $\pi_3 A(U) \delta \pi_3 A(V) = \{x\} \delta \{z\}$ iff $\pi_3 S(U) \delta \pi_3 S(V) = \{y\} \delta \{w\}$.

If $U = \{(x, y)_1\}$ and $V = \{(z, w)_2\}$, then $\pi_1 A(U) \delta \pi_1 A(V) = \{x\} \delta \{z\} = \pi_1 S(U) \delta \pi_1 S(V)$, $\pi_2 A(U) \delta \pi_2 A(V) = \{y\} \delta \{z\} = \pi_2 S(U) \delta \pi_2 S(V)$. Note that $\pi_3 A(U) \delta \pi_3 A(V) = \{x\} \delta \{w\}$ iff $\pi_3 S(U) \delta \pi_3 S(V) = \{y\} \delta \{w\}$, (since δ is an Efremovich proximity structure).

If $U = \{(x, y)_1\}$ and $V = \{(z, z)\}$, then $\pi_1 A(U) \delta \pi_1 A(V) = \{x\} \delta \{z\} = \pi_1 S(U) \delta \pi_1 S(V)$, $\pi_2 A(U) \delta \pi_2 A(V) = \{y\} \delta \{z\} = \pi_2 S(U) \delta \pi_2 S(V)$, clearly, $\pi_3 A(U) \delta \pi_3 A(V) = \{x\} \delta \{z\}$ iff $\pi_3 S(U) \delta \pi_3 S(V) = \{y\} \delta \{z\}$.

Similarly, if $U = \{(x, y)_2\}$ or $\{(x, x)\}$ and $V = \{(z, w)_1\}, \{(z, w)_2\}$ or $\{(z, z)\}$, then we have $\pi_1 A(U) \delta \pi_1 A(V)$, $\pi_2 A(U) \delta \pi_2 A(V)$ and $\pi_3 A(U) \delta \pi_3 A(V)$ iff $\pi_1 S(U) \delta \pi_1 S(V)$, $\pi_2 S(U) \delta \pi_2 S(V)$ and $\pi_3 S(U) \delta \pi_3 S(V)$, respectively.

Hence (X, δ) is $Pre\bar{T}_2$. \square

Theorem 3.8. An Efremovich proximity space (X, δ) is $PreT'_2$ if and only if, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.

Proof. Suppose (X, δ) is $PreT'_2$, i.e., by 2.4, 2.6 and Definition 3.1, for any sets U, V on $X^2 \vee_{\Delta} X^2$, (a) $\pi_{11} U \delta \pi_{11} V$, $\pi_{21} U \delta \pi_{21} V$ and $\pi_{22} U \delta \pi_{22} V$ iff (b) there exists a pair $(a, b), (c, d) \in X^2$ such that $(\{a, b\}) \delta^2 \{(c, d)\}$ and $i_k\{a, b\} = U$ and $i_k\{c, d\} = V$ for some $k = 1$ or 2 , where δ^2 is the product proximity structure on X^2 .

For each pair U, V in the different component of $X^2 \vee_{\Delta} X^2$, $U \delta' V$ iff there exist sets C, D and A in X^2 such that $C \delta^2 A$ and $A \delta^2 D$ with $i_k^{-1}(U) = C$ and $i_j^{-1}(V) = D$ for $k, j = 1, 2$ and $k \neq j$. If U and V are in the same component of wedge, then $U \delta' V$ iff there exist sets C, D in X^2 such that $C \delta^2 D$ and $i_k^{-1}(U) = C$ and $i_k^{-1}(V) = D$ for some $k = 1, 2$. Specially, if $i_k(E) = U$ and $i_k(F) = V$, then $(i_k(E), i_k(F)) \in \delta'$ iff $(i_k^{-1}(i_k(E)), i_k^{-1}(i_k(F))) = (E, F) \in \delta^2$. This is a special case of 2.5. We shall show that the condition holds.

Suppose for some $x, y \in X$, $(\{x\}, \{y\}) \in \delta$ with $x \neq y$. Then, for $(U, V) \in \delta'$ (δ' is an Efremovich proximity structure on $X^2 \vee_{\Delta} X^2$) with $U \supseteq \{(x, y)_1\}$ and $V \supseteq \{(x, y)_2\}$, $\pi_{11}U \delta \pi_{11}V \supseteq \pi_1S\{(x, y)_1\} \delta \pi_1S\{(x, y)_2\} = \pi_1\{(x, y, y)\} \delta \pi_1\{(x, x, y)\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_{21}U \delta \pi_{21}V \supseteq \pi_2S\{(x, y)_1\} \delta \pi_2S\{(x, y)_2\} = \pi_2\{(x, y, y)\} \delta \pi_2\{(x, x, y)\} = \{y\} \delta \{x\}$, i.e., $(\{y\}, \{x\}) \in \delta$, $\pi_{22}U \delta \pi_{22}V \supseteq \pi_3S\{(x, y)_1\} \delta \pi_3S\{(x, y)_2\} = \pi_3\{(x, y, y)\} \delta \pi_3\{(x, x, y)\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, where $\pi_i : X^3 \rightarrow X$, ($i = 1, 2, 3$), are the projection maps.

There exist sets E, F and A in X^2 such that $E \delta^2 A$ and $A \delta^2 F$ with $i_k^{-1}(U) = E$ and $i_j^{-1}(V) = F$ for $k, j = 1, 2$ and $k \neq j$. $i_k(i_k^{-1}(U)) = i_k(E) \subseteq U$ and $i_j(i_j^{-1}(V)) = i_j(F) \subseteq V$.

If $i_k(E)$ subset of the first component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of the second component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_1\} \subseteq i_k(E)$ and $\{(x, y)_2\} \subseteq i_k(F)$. But, if $(i_k(E), i_k(F)) \supseteq (\{(x, y)_1\}, \{(x, y)_2\}) \in \delta'$ for some $(E, F) \in \delta^2$ and $k = 1$ (resp. $k = 2$), then $(\{(x, y)_1\}, \{(x, y)_2\}) \supseteq (i_1(E), i_1(F))$ which shows that $(x, y)_2$ (resp. $(x, y)_1$) must be in the first (resp. second) component of $X^2 \vee_{\Delta} X^2$, a contradiction since $x \neq y$.

Similarly, if $i_k(E)$ subset of the second component of $X^2 \vee_{\Delta} X^2$ and $i_k(F)$ subset of the first component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_2\} \subseteq i_k(E)$ and $\{(x, y)_1\} \subseteq i_k(F)$. But, if $(i_k(E), i_k(F)) \supseteq (\{(x, y)_2\}, \{(x, y)_1\}) \in \delta'$ for some $(E, F) \in \delta^2$ and $k = 1$ (resp. $k = 2$), then $(\{(x, y)_2\}, \{(x, y)_1\}) \in (i_1(E), i_1(F))$ which shows that $(x, y)_2$ (resp. $(x, y)_1$) must be in the first (resp. second) component of $X^2 \vee_{\Delta} X^2$, a contradiction since $x \neq y$. Hence $i_k(E)$ and $i_k(F)$ can not be in different component of $X^2 \vee_{\Delta} X^2$.

Conversely, suppose that for each $x \neq y$, $(\{x\}, \{y\}) \notin \delta$. We need to show that (X, δ) is $PreT'_2$, i.e., by 2.4, 2.6 and 3.1, (a) and (b) above are equivalent. We first show that (a) implies (b). Let (U, V) be any set in δ' , i.e., $\pi_iS(U) \delta \pi_iS(V)$ ($i = 1, 2, 3$).

If $i_k(E) \subseteq U$ subset of the first component of $X^2 \vee_{\Delta} X^2$ and $i_k(F) \subseteq V$ subset of the second component of $X^2 \vee_{\Delta} X^2$, then $\{(x, y)_1\} \supseteq i_k(E)$ and $\{(x, y)_2\} \supseteq i_k(F)$. It follows that $\pi_2S\{(x, y)_1\} \delta \pi_2S\{(x, y)_2\} = \pi_2\{(x, y, y)\} \delta \pi_2\{(x, x, y)\} = \{y\} \delta \{x\}$, i.e., $(\{y\}, \{x\}) \in \delta$. Since $(\{x\}, \{y\}) \notin \delta$ (by assumption), $(\{(x, y)_1\}, \{(x, y)_2\}) \notin \delta'$ by the condition (P2) of 2.1.

The case $i_k(E) \subseteq U$ subset of the second component of $X^2 \vee_{\Delta} X^2$ and $i_k(F) \subseteq V$ subset of the first component of $X^2 \vee_{\Delta} X^2$ can be handled similarly. Hence $i_k(E)$ and $i_k(F)$ can not be in different component of $X^2 \vee_{\Delta} X^2$.

If $i_k(E) \subseteq U$ and $i_k(F) \subseteq V$ are in both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq i_k(E) \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq i_k(F) \supseteq \{(x, y)_1, (x, y)_2\}$.

If $i_k(E) \subseteq U$ subset of the first component of $X^2 \vee_{\Delta} X^2$ and $i_k(F) \subseteq V$ subset of both component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq i_k(E) \supseteq \{(x, y)_1\}$ and $V \supseteq i_k(F) \supseteq \{(x, y)_1, (x, y)_2\}$.

If $i_k(E) \subseteq U$ subset of both component of $X^2 \vee_{\Delta} X^2$ and $i_k(F) \subseteq V$ subset of the second component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq i_k(E) \supseteq \{(x, y)_1, (x, y)_2\}$ and $V \supseteq i_k(F) \supseteq \{(x, y)_2\}$.

If $i_k(E) \subseteq U$ and $i_k(F) \subseteq V$ are in the first component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq i_k(E) \supseteq \{(x, y)_1\}$ and $V \supseteq i_k(F) \supseteq \{(x, y)_1\}$. Similarly if $i_k(E) \subseteq U$ and $i_k(F) \subseteq V$ are in the second component of $X^2 \vee_{\Delta} X^2$, then $U \supseteq i_k(E) \supseteq \{(x, y)_2\}$ and $V \supseteq i_k(F) \supseteq \{(x, y)_2\}$.

If $(\{(x, y)_i\}, \{(x, y)_i\}) \in \delta'$, ($i = 1, 2$), then $\pi_1S\{(x, y)_1\} \delta \pi_1S\{(x, y)_1\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2S\{(x, y)_1\} \delta \pi_2S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, $\pi_3S\{(x, y)_1\} \delta \pi_3S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$ and $\pi_1S\{(x, y)_2\} \delta \pi_1S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2S\{(x, y)_2\} \delta \pi_2S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_3S\{(x, y)_2\} \delta \pi_3S\{(x, y)_2\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$.

It follows that $(i_k(E), i_k(F)) \supseteq (\{(x, y)_i\}, \{(x, y)_i\})$, ($i = 1, 2$), i.e., $i_k(E) \subseteq U$ and $i_k(F) \subseteq V$ are in the first or in the second or in both component of $X^2 \vee_{\Delta} X^2$. So there exists a pair $(a, b), (c, d) \in X^2$ such that $\{(a, b)\} \delta^2 \{(c, d)\}$ and $i_k\{(a, b)\} = U$ and $i_k\{(c, d)\} = V$ for some $k = 1$ or 2 . This shows that (a) implies (b).

We now show that (b) implies (a). Suppose (b) holds. We need to show that for any sets U, V on $X^2 \vee_{\Delta} X^2$, $\pi_{11}U \delta \pi_{11}V$, $\pi_{21}U \delta \pi_{21}V$ and $\pi_{22}U \delta \pi_{22}V$. There exists a pair $(a, b), (c, d) \in X^2$ such that $\{(a, b)\} \delta^2 \{(c, d)\}$ and $i_k\{(a, b)\} = U$ and $i_k\{(c, d)\} = V$ for some $k = 1$ or 2 . By using the similar argument as above, we must have $(i_k\{(a, b)\}, i_k\{(c, d)\}) \supseteq (\{(x, y)_i\}, \{(x, y)_i\})$, ($i = 1, 2$). For $i = 1$ if $(\{(x, y)_1\}, \{(x, y)_1\}) \in \delta'$,

then $\pi_1 S\{(x, y)_1\} \delta \pi_1 S\{(x, y)_1\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2 S\{(x, y)_1\} \delta \pi_2 S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$, $\pi_3 S\{(x, y)_1\} \delta \pi_3 S\{(x, y)_1\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$. For $i = 2$ if $(\{(x, y)_2\}, \{(x, y)_2\}) \in \delta'$, then $\pi_1 S\{(x, y)_2\} \delta \pi_1 S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_2 S\{(x, y)_2\} \delta \pi_2 S\{(x, y)_2\} = \{x\} \delta \{x\}$, i.e., $(\{x\}, \{x\}) \in \delta$, $\pi_3 S\{(x, y)_2\} \delta \pi_3 S\{(x, y)_2\} = \{y\} \delta \{y\}$, i.e., $(\{y\}, \{y\}) \in \delta$. Hence $\pi_i S(U) \delta \pi_i S(V)$ ($i = 1, 2, 3$). This shows that (b) implies (a).

Hence (X, δ) is $PreT'_2$. \square

Remark 3.9. If an Efremovich proximity space (X, δ) is $PreT'_2$, then it is $Pre\bar{T}_2$. However, the converse is not true generally. For example, let $X = \{1, 2\}$ and $\delta = \{(X, X), (\{1\}, \{1\}), (\{2\}, \{2\}), (X, \{1\}), (\{1\}, X), (X, \{2\}), (\{2\}, X), (\{1\}, \{2\}), (\{2\}, \{1\})\}$. Then (X, δ) is $Pre\bar{T}_2$, but it is not $PreT'_2$ since $(\{1\}, \{2\}) \in \delta$ but $1 \neq 2$.

Theorem 3.10. An Efremovich proximity space (X, δ) is \bar{T}_2 iff, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.

Proof. It follows from Definition 3.1 and Theorems 3.3, 3.7. \square

Theorem 3.11. An Efremovich proximity space (X, δ) is T'_2 iff, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.

Proof. It follows from Definition 3.1 and Theorems 3.4, 3.8. \square

4. T_0 and T_1 Proximity Spaces at a Point p and Relationships

Let B be set and $p \in B$. Let $B \vee_p B$ be the wedge at p ([2] p. 334), i.e., two disjoint copies of B identified at p , or in other words, the pushout of $p : 1 \rightarrow B$ along itself (where 1 is the terminal object in **Set**, the category of sets). More precisely, if i_1 and $i_2 : B \rightarrow B \vee_p B$ denote the inclusion of B as the first and second factor, respectively, then $i_1 p = i_2 p$ is the pushout diagram. A point x in $B \vee_p B$ will be denoted by $x_1(x_2)$ if x is in the first (resp. second) component of $B \vee_p B$. Note that $p_1 = p_2$.

The principal p -axis map, $A_p : B \vee_p B \rightarrow B^2$ is defined by $A_p(x_1) = (x, p)$ and $A_p(x_2) = (p, x)$. The skewed p -axis map, $S_p : B \vee_p B \rightarrow B^2$ is defined by $S_p(x_1) = (x, x)$ and $S_p(x_2) = (p, x)$. The fold map at p , $\nabla_p : B \vee_p B \rightarrow B$ is given by $\nabla_p(x_i) = x$ for $i = 1, 2$ [2, 4].

Note that the maps A_p , S_p and ∇_p are the unique maps arising from the above pushout diagram for which $A_p i_1 = (id, f)$, $S_p i_1 = (id, id) : B \rightarrow B^2$, $A_p i_2 = S_p i_2 = (f, id) : B \rightarrow B^2$, and $\nabla_p i_j = id$, $j = 1, 2$, respectively, where, $id : B \rightarrow B$ is the identity map and $f : B \rightarrow B$ is the constant map at p [2].

Remark 4.1. We define p_1, p_2 by $1 + p, p + 1 : B \vee_p B \rightarrow B$, respectively where $1 : B \rightarrow B$ is the identity map, $f : B \rightarrow B$ is constant map at p (i.e., having value p). Note that $\pi_1 A_p = p_1 = \pi_1 S_p$, $\pi_2 A_p = p_2$, $\pi_2 S_p = \nabla_p$, where $\pi_i : B^2 \rightarrow B$ is the i -th projection, $i = 1, 2$. When showing A_p and S_p are initial it is sufficient to show that $(p_1$ and $p_2)$ and $(p_1$ and $\nabla_p)$ are initial lifts, respectively [2, 4].

Definition 4.2. [2] Let $\mathcal{U} : \mathcal{E} \rightarrow \mathbf{Set}$ be a topological functor, X an object in \mathcal{E} , and p be a point in $\mathcal{U}(X) = B$.

1. X is \bar{T}_0 at p iff the initial lift of the \mathcal{U} -source $\{A_p : B \vee_p B \rightarrow \mathcal{U}(X^2) = B^2$ and $\nabla_p : B \vee_p B \rightarrow \mathcal{U}\mathcal{D}(B) = B\}$ is discrete, where \mathcal{D} is the discrete functor which is a left adjoint to \mathcal{U} .
2. X is T'_0 at p iff the initial lift of the \mathcal{U} -source $\{id : B \vee_p B \rightarrow \mathcal{U}(X \vee_p X) = B \vee_p B$ and $\nabla_p : B \vee_p B \rightarrow \mathcal{U}\mathcal{D}(B) = B\}$ is discrete, where $X \vee_p X$ is the wedge in \mathcal{E} i.e., the final lift of the \mathcal{U} -sink $\{i_1, i_2 : \mathcal{U}(X) = B \rightarrow B \vee_p B\}$ where i_1, i_2 denote the canonical injections.
3. X is T_1 at p iff the initial lift of the \mathcal{U} -source $\{S_p : B \vee_p B \rightarrow \mathcal{U}(X^2) = B^2$ and $\nabla_p : B \vee_p B \rightarrow \mathcal{U}\mathcal{D}(B) = B\}$ is discrete.

Remark 4.3. Note that for the category **Top** of topological spaces, \bar{T}_0 at p , T'_0 at p , or T_1 at p reduce to usual T_0 at p or T_1 at p , respectively, where a topological space X is called T_0 at p (resp. T_1 at p) if for each $x \neq p$, there exists a neighborhood of x not containing p or (resp. and) there exists a neighborhood of p not containing x [7].

Theorem 4.4. Let (X, δ) be an Efremovich proximity space and $p \in X$. (X, δ) is T_1 at p iff, for each $x \neq p$, $(\{x\}, \{p\}) \notin \delta$ [25].

Theorem 4.5. Let (X, δ) be an Efremovich proximity space and $p \in X$. (X, δ) is \bar{T}_0 at p iff, for each $x \neq p$, $(\{x\}, \{p\}) \notin \delta$ [25].

Remark 4.6. Let (X, δ) be an Efremovich proximity space and $p \in X$. It follows from 4.4, 4.5 that (X, δ) is \bar{T}_0 at p if and only if (X, δ) is T_1 at p if and only if, for each $x \neq p$, $(\{x\}, \{p\}) \notin \delta$ [25].

Theorem 4.7. An Efremovich proximity space is T'_0 at p [25].

Remark 4.8. If an Efremovich proximity space (X, δ) is \bar{T}_0 at $p \in X$ or T_1 at $p \in X$, then it is T'_0 at p . However, the converse is not true generally. For example, let $X = \{a, b\}$ and $\delta = \{(X, X), (\{a\}, \{a\}), (\{b\}, \{b\}), (X, \{a\}), (\{a\}, X), (X, \{b\}), (\{b\}, X), (\{a\}, \{b\}), (\{b\}, \{a\})\}$. Then (X, δ) is T'_0 at $p = a$ but it is not \bar{T}_0 at $p = a$ or T_1 at p since $(\{a\}, \{b\}) \in \delta$ but $a \neq b$ [25].

Definition 4.9. [28, 32] An Efremovich proximity space (X, δ) is said to be a

- **T_0 -space** if $x \neq y$ for $x, y \in X$ implies that $x \not\delta y$.
- **T_1 -space** if $x \neq y$ for $x, y \in X$ implies that $x \not\delta y$.
- **T_2 -space (Hausdorff)** if $x \delta y$ for $x, y \in X$ implies that $x = y$.

We give explicit relationships among the generalized separation properties T_0 and T_1 , the separation properties at a point p and separation properties T_i , $i = 0, 1, 2$ in Definition 4.9 in the topological category of proximity spaces.

Remark 4.10. Let (X, δ) be an Efremovich proximity space.

- (i) By Theorems 3.3, 3.5, 3.8, 3.10, 3.11, and Definition 4.9, (X, δ) is \bar{T}_0 if and only if (X, δ) is \mathbf{T}_0 if and only if (X, δ) is T_1 if and only if (X, δ) is \mathbf{T}_1 if and only if (X, δ) is $PreT'_2$ if and only if (X, δ) is \bar{T}_2 if and only if (X, δ) is T'_2 if and only if (X, δ) is \mathbf{T}_2 if and only if, for each distinct pair x and y in X , $(\{x\}, \{y\}) \notin \delta$.
- (ii) By Theorems 3.3, 3.4, 3.5, 3.7, 3.8, 3.10, 3.11, and Definition 4.9, (X, δ) is T'_0 or $Pre\bar{T}_2$ if (X, δ) is \bar{T}_0 or \mathbf{T}_0 or T_1 or \mathbf{T}_1 or $PreT'_2$ or \bar{T}_2 or T'_2 or \mathbf{T}_2 . But the converse implication is not true, in general. For example, let $X = \{x, y\}$ and $\delta = \{(X, X), (\{x\}, \{x\}), (\{y\}, \{y\}), (X, \{x\}), (\{x\}, X), (X, \{y\}), (\{y\}, X), (\{x\}, \{y\}), (\{y\}, \{x\})\}$. Then (X, δ) is T'_0 and $Pre\bar{T}_2$ but it is not \bar{T}_0 or \mathbf{T}_0 or T_1 or \mathbf{T}_1 or $PreT'_2$ or \bar{T}_2 or T'_2 or \mathbf{T}_2 , since $(\{x\}, \{y\}) \in \delta$ but $x \neq y$.
- (iii) By Theorems 3.4, 3.7 and 4.7, (X, δ) is $Pre\bar{T}_2$ if and only if (X, δ) is T'_0 if and only if (X, δ) is T'_0 at p for all points p in X .

We can infer the following result.

Remark 4.11. Let (X, δ) be an Efremovich proximity space. By Theorems 3.3, 3.5, 3.8, 3.10, 3.11, 4.4, 4.5, Definition 4.9, and Remark 4.10 then the following are equivalent:

- (i) (X, δ) is \bar{T}_0 .
- (ii) (X, δ) is \mathbf{T}_0 .
- (iii) (X, δ) is T_1 .
- (iv) (X, δ) is \mathbf{T}_1 .
- (v) (X, δ) is $PreT'_2$.
- (vi) (X, δ) is \bar{T}_2 .
- (vii) (X, δ) is T'_2 .
- (viii) (X, δ) is \mathbf{T}_2 .
- (ix) For any distinct pair of points x and y in X , $(\{x\}, \{y\}) \notin \delta$.
- (x) (X, δ) is T_1 at p for all points p in X .
- (xi) (X, δ) is \bar{T}_0 at p for all points p in X .

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