# Hausdorff Dimension of the Nondifferentiability Set of a Convex Function 

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#### Abstract

We find an upper bound for the Hausdorff dimension of the nondifferentiability set of a continuous convex function defined on a Riemannian manifold. As an application, we show that the boundary of a convex open subset of $R^{n}, n \geq 2$, has Hausdorff dimension at most $n-2$.


## 1. Introduction

There are many examples of nowhere differentiable continuous functions defined on a differentiable manifold $M$. In fact, the set of this kind of functions is very big in some points of view. For example, it is proved in [4] that if $M$ is a compact differentiable manifold, then typical elements of the set of continuous functions defined on $M$ are nowhere differentiable. If we impose some important conditions such convexity or Lipschitz condition on a continuous function $f$, then $f$ is not nowhere differentiable. So, it is natural to ask: how big can be the set of nondifferentiability points of $f$. The set of nondifferentiability points of a directionally differentiable Lipschitz-function $f$ defined on $R^{n}$ is $\sigma$-porous (see [1]). Thus, it can be included in a countable union of sets $E_{i}$ with the property that for all $x \in E_{i}$ and all $0<r<1$, there exists $0<\delta_{i}(x)<\frac{1}{2}$ such that a ball $B(y, \delta r)$ is included in $B(x, r)-E_{i}$. This argument also implies the best Hausdorff dimension estimate, $n-1$, for the set of nondifferentiability.

Also, one can find some measure theoric characterizations of the magnitude of the sets of nondifferentiability points of convex functions defined on $R^{n}$ (see [5]). In the present paper, by a preliminary proof, we give an upper bound estimate for the Hausdorff dimension of the set of nondifferentiability points of convex functions defined on $R^{n}$, then we generalize it to the convex functions defined on Riemannian manifolds.

## 2. Results

We will use the following definitions and facts in the proof of our theorems.
(a) A continuous function $f: R^{n} \rightarrow R$ is called convex if for all $x, y \in R^{n}$

$$
a f(x)+(1-a) f(y) \leq f(a x+(1-a) y), \quad 0 \leq a \leq 1 .
$$

[^0]and it is called concave if for all $x, y \in R^{n}$
$$
a f(x)+(1-a) f(y) \geq f(a x+(1-a) y), \quad 0 \leq a \leq 1
$$
(b) Let $X$ be a metric space. If $A \subset X$ and $s \in[0, \infty)$, we put
$$
H_{\delta}^{s}(A)=\inf \left\{\sum_{i} r_{i}^{s}: \text { there is a cover of } \mathrm{A} \text { by balls of radius } 0<r_{i} \leq \delta\right\}
$$

The following limit which exits (see [3]), is called the s-dimensional Hausdorff content of $A$.

$$
H^{s}(A)=\lim _{\delta \rightarrow 0} H_{\delta}^{s}(A)
$$

The Hausdorff dimension of $A$ is defined by

$$
\operatorname{dim}_{H}(A)=\inf \left\{s: H^{s}(A)=0\right\}
$$

Fact 2.1. Let $B$ be the collection of all line segments in $R^{2}$ which have rational coordinates at the end points. If $L$ is a line segment in $R^{2}$, it is clear that there is a line segment in $B$ which cuts $L$. So, it is not hard to show that each line segment in $R^{3}$ cuts a triangle in $R^{3}$ with vertices having rational coordinates. In more general case, by using induction, we can show that each line segment in $R^{n}$ cuts an ( $n-1$ )-simplex with vertices having rational coordinates.

Fact 2.2. If $f: R \rightarrow R$ is a convex or concave continuous function, then the set of points where $f$ is not differentiable is at most a countable set, so its Hausdorff dimension is zero.

The following theorem is a generalization of this fact.
Theorem 2.3. The Hausdorff dimension of the set of nondifferentiability points of a convex or concave function $f: R^{n} \rightarrow R$ is at most $n-1$.

Proof. The ideas of the proof comes from the proof of Theorem 12.3 in [3]. We give the proof for convex functions. The other case is similar. Without lose of generality, we suppose that $f$ is positive function. Consider the graph of $f, \mathcal{G}_{f}=\left\{(x, f(x)): x \in R^{n}\right\} \subset R^{n+1}$. For each $x \in R^{n}$, let $g(x)$ be the point in $\mathcal{G}_{f}$ which the distance between $(x, 0) \in R^{n} \times R=R^{n+1}$ and $g(x)$ is least. We get from convexity of $f$ that the map $g: R^{n} \rightarrow \mathcal{G}_{f}$ is well defined. Given $(y, f(y)) \in \mathcal{G}_{f}$, let $T_{y}$ be a hyperplane in $R^{n+1}$ which is tangent to $\mathcal{G}_{f}$ at $(y, f(y))$, and let $L_{y}$ be the line in $R^{n+1}$ which is perpendicular to $T_{y}$ at $(y, f(y))$. Clearly, if $(x, 0)=L_{y} \cap\left(R^{n} \times\{0\}\right)$, then $g(x)=(y, f(y))$. If $f$ is not differentiable at $y$, then there are infinitely many hyperplanes tangent to $\mathcal{G}_{f}$ at ( $y, f(y)$ ) and infinitely many $L y$ such that intersection of these lines $L_{y}$ with $R^{n} \times\{0\}$ at least contains a line segment in $R^{n} \times\{0\} \simeq R^{n}$. Put
$A=\{(y, f(y)): f$ is not differentiable at $y\}$ and
$B=$ the union of all $(n-1)$-simplexes in $R^{n}$ with vertices having rational coordinates.
Since for each point $(y, f(y)) \in(A)$, the set $g^{-1}((y, f(y)))$ contains a line segment, then it intersects at least one ( $n-1$ )-simplex in $R^{n}$ with vertices having rational coordinates. So, $A \subset g(B)$. We can show that $d(g(x), g(y)) \leq d(x, y), x, y \in R^{n}$. Thus, $\operatorname{dim}_{H}(A) \leq \operatorname{dim}_{H} g(B) \leq \operatorname{dim}_{H}(B)$. Since $\operatorname{dim}_{H}(B)=n-1$, then $\operatorname{dim}_{H}(A) \leq n-1$. Now, consider the function $F: R^{n} \rightarrow R^{n+1}$, defined by $F(x)=(x, f(x))$. The points of $R^{n}$ where $F$ is not differentiable is equal to the set of points where $f$ is not differentiable, and this set is mapped by $F$ to $A$. Since $d(F(x), F(y)) \geq d(x, y)$, then the theorem is proved.

Example 2.4. An easy example of a convex function with infinite set of nondifferentiability points is the function $h:[0,1] \rightarrow R$ defined by $h(x)=\sum_{n=1}^{\infty} 2^{-n}\left|x-\frac{1}{n}\right|$. $h$ can be extended to a convex function $g: R \rightarrow R$ in such a way that $g$ be differentiable on $R-[0,1]$. The set of nondifferentiability points of $g$, which we denote it by $\mathcal{A}_{g}$, is countable and $\operatorname{dim}_{H}\left(\mathcal{A}_{g}\right)=0$. Put $f: R^{n} \rightarrow R, f\left(x_{1}, \ldots, x_{n}\right)=g\left(x_{1}\right)$. Clearly, $f$ is convex and $\mathcal{A}_{f}$, the set of nondifferentiability points of $f$, is equal to $\mathcal{A}_{g} \times R^{n-1}$. Thus, $\operatorname{dim}_{H} \mathcal{A}_{f}=n-1$.

Theorem 2.5. If $M$ is a submanifold of $R^{n+1}$ contained in the boundary of a convex open subset of $R^{n+1}$, then the Hausdorff dimension of nondifferentiable points of $M$ is at most $n-1$.

Proof. We show that $M$ is locally isometric to the graph of a convex function. Then, by Theorem 2.3, we get the result. Let $D$ be an open convex subset of $R^{n+1}$ such that $M=\partial D$ and let $a \in M$. Consider an open subset $W$ of a hyperplane in $R^{n+1}$ with the following properties:
(1) $W \subset D$;
(2) There is a unit vector $V$ perpendicular to $W$ at a point $y_{0}$, such that the half line $y_{0}+t V, t \geq 0$, contains $a$, and for all $y \in W$, the half line $y+t V, t \geq 0$, intersects $M$.
Let $M_{1}$ be the set of points of $M$ belonging to the mentioned half lines. Clearly $M_{1}$ is open set in $M$ containing a.

Given $x \in W$, let $\tau(x)$ be the intersection point of the half line $x+t V, t \geq 0$, and $M_{1}$. Consider the function $f: W \rightarrow R, f(x)=|\tau(x)-x|$. It is sufficient to prove the following assertions:
(1) $f$ is well defined;
(2) $f$ is convex;
(3) $\operatorname{graph}(f) \subset W \times R$ is isometric to $M_{1} \subset R^{n+1}$.
(1): Consider a point $x \in W$. We show that the intersection point of the half line $L=\{x+t V, t \geq 0\}$ and $M_{1}$ is unique. Then, $f$ will be well defined. Let $y_{1}$ and $y_{2}$ be two different points belonging to $L \cap M_{1}$. Let one of the points $y_{1}, y_{2}$, say $y_{1}$, is contained between the points $x$ and $y_{2}$ on the half line $L$. Since $y_{2}$ belongs to the boundary of $D$ and $D$ is open, by an small rotation of the line segment $x y_{2}$ around the point $y_{1}$, we get a line segment $x^{\prime} y_{2}^{\prime}$ with $x^{\prime}, y_{2}^{\prime} \in D$. $D$ is convex, so $y_{1} \in D$ and we have a contradiction.
(2): Let $0 \leq \lambda \leq 1$ and $x, y \in D$. Note that if $x+s V=\tau(x)$ then the half open line segment $\{x+t V: 0 \leq t<s\}$ is included in $D$.

We show that

$$
\begin{equation*}
f(\lambda x+(1-\lambda) y) \geq \lambda f(x)+(1-\lambda) f(y) \tag{1}
\end{equation*}
$$

Let $\tau(x)=x+s_{1} V, \tau(y)=y+s_{2} V$. Then, for any positive number $\epsilon<\min \left\{s_{1}, s_{2}\right\}, x+\left(s_{1}-\epsilon\right) V, y+\left(s_{2}-\epsilon\right) V \in D$. Thus, by convexity of $D$,

$$
\begin{equation*}
A_{\epsilon}=\lambda\left(x+\left(s_{1}-\epsilon\right) V\right)+(1-\lambda)\left(y+\left(s_{2}-\epsilon\right) V\right) \in D \tag{2}
\end{equation*}
$$

Put $B=\lambda \tau(x)+(1-\lambda) \tau(y), C_{1}=\lambda x+(1-\lambda) y$ and $C=\tau\left(C_{1}\right)=C_{1}+s_{3} V$. It is an easy computation to show that $B$ (as like as $C$ ) belongs to the half line $\left\{C_{1}+t V: t \geq 0\right\}$. Let $B=C_{1}+s_{4} V$. Since $\lim _{\epsilon \rightarrow 0} A_{\epsilon}=B$, then $B \in \bar{D}$, so $s_{4} \leq s_{3}$.

Now, we have

$$
\begin{aligned}
& f(\lambda x+(1-\lambda) y)=f\left(C_{1}\right)=\left|\tau\left(C_{1}\right)-C_{1}\right|=s_{3}|V| \geq s_{4}|V| \\
& =\left|B-C_{1}\right|=|\lambda \tau(x)+(1-\lambda) \tau(y)-(\lambda x+(1-\lambda) y)| \\
& =|\lambda(\tau(x)-x)+(1-\lambda)(\tau(y)-y)| .
\end{aligned}
$$

Since the vectors $\tau(x)-x$ and $\tau(y)-y$ in $R^{n+1}$ are both perpendicular to the hyperplane $W$, then

$$
\begin{aligned}
& |\lambda(\tau(x)-x)+(1-\lambda)(\tau(y)-y)|=|\lambda(\tau(x)-x)|+|(1-\lambda)(\tau(y)-y)| \\
& =\lambda f(x)+(1-\lambda) f(y)
\end{aligned}
$$

Thus,

$$
f(\lambda x+(1-\lambda) y) \geq \lambda f(x)+(1-\lambda) f(y)
$$

(3) Define the map $\psi: \operatorname{graph}(f) \subset W \times R \rightarrow M_{1} \subset R^{n+1}$ by

$$
\psi(x, f(x))=x+|\tau(x)-x| V .
$$

Clearly, $\psi$ is one to one and onto, and we have:

$$
\begin{aligned}
& d^{2}(\psi(x, f(x)), \psi(y, f(y)))=|\psi(x, f(x))-\psi(y, f(y))|^{2} \\
& =|(x+|\tau(x)-x| V)-(y+|\tau(y)-y| V)|^{2}
\end{aligned}
$$

Since $x, y$ belong to the hyperplane $W$, and $V$ is perpendicular to $W$, then $(\star)$ will be equal to

$$
\begin{aligned}
& |(x-y)|^{2}+|(x-\tau(x))-(y-\tau(y))|^{2}=|x-y|^{2}+|f(x)-f(y)|^{2} \\
& =d^{2}((x, f(x)),(y, f(y))) .
\end{aligned}
$$

Thus, $\psi$ is an isometry.
Example 2.6. Let $\Delta$ be a triangle in $R^{2}$ with vertices $A, B, C$, and $\Delta^{o}$ be its interior. Put $M=\Delta \times R^{n-1}$. $M$ is boundary of the convex set $\Delta^{0} \times R^{n-1} \subset R^{n+1}$. The set of nondifferentiability points of $M$ is equal to $\{A, B, C\} \times R^{n-1}$, which is of Hausdorff dimension $n-1$.

Remark 2.7. If $M$ is a Riemannian manifold, a function $f: M \rightarrow R$ is called convex if for each geodesic $\gamma: I \rightarrow M$, the function $f \circ \gamma: I \rightarrow R$ is convex.
Theorem 2.8. If $M$ is a complete Riemannian manifold and $f: M \rightarrow R$ is a convex function, then the Hausdorff dimension of nondifferentiability set of $f$ is at most $\operatorname{dim} M-1$.

Proof. It is sufficient to show that each point $a \in M$ has an open neighborhood $W$ such that the theorem is true for the function $f: W \rightarrow R$. By Nash's embedding theorem, $M$ can be considered as a Riemannian submanifold of $R^{n}$ for some $n>\operatorname{dim} M$. Given $a \in M$, consider an open set $W$ in $M$ around $a$ with compact closure $\bar{W}$. There exists a tube $U=U(W, r)=\left\{x \in R^{n}: d(x, W)<r\right\}$ of radius $r$ around $W$ in $R^{n}$, with the property that for each $x \in U$, there exists only one point $x_{w} \in W$ such that

$$
d(x, W)=d\left(x, x_{w}\right)
$$

Now, consider the following function which is an extension of $f$ to $U$

$$
F: U \subset R^{n} \rightarrow R, F(x)=f\left(x_{\mathrm{w}}\right)
$$

We show that $F$ is a convex function.
Let $x, y \in U$ and $0 \leq \lambda \leq 1$. Put $z=\lambda x+(1-\lambda) y$. Consider the points $x_{M}, y_{M}, z_{w}$ in $W$ with the property $(\star)$. Let $\alpha, \beta$ be geodesics in $W$ such that $\alpha(0)=x_{w}, \alpha(1)=z_{w}=\beta(1)$ and $\beta(0)=y_{w}$.

Consider the points $x_{s}=\alpha(s)$ and $y_{s}=\beta(s), 0<s<1$, on $\alpha$ and $\beta$, close to $z_{\mathrm{w}}$ such that there is a minimizing geodesic $\gamma_{s}:[0,1] \rightarrow W$ joining $x_{s}$ to $y_{s}$. Since $f$ is convex on $W$, then

$$
\begin{align*}
& f\left(\gamma_{s}(\lambda)\right) \leq \lambda f(\alpha(s))+(1-\lambda) f(\beta(s))  \tag{1}\\
& f(\alpha(s)) \leq s f\left(x_{W}\right)+(1-s) f\left(z_{W}\right)  \tag{2}\\
& f(\beta(s)) \leq(1-s) f\left(z_{M}\right)+s f\left(y_{W}\right) \tag{3}
\end{align*}
$$

If $s \rightarrow 1$ then $\gamma_{s}(\lambda) \rightarrow z_{w}$, so if we let $s \rightarrow 1$ in (1), (2) and (3), then we get

$$
f\left(z_{w}\right) \leq \lambda f\left(x_{w}\right)+(1-\lambda) f\left(y_{w}\right) .
$$

Therefore,

$$
F(z) \leq \lambda F(x)+(1-\lambda) F(y)
$$

This means that $F$ is convex. Since $U$ is open in $R^{n}$, we get from Theorem 2.3, that the dimension of the set of nondifferentiability points of $F$ is at most $n-1$. Consider a point $x \in U$. If $f$ is not differentiable at $x_{w}$ then $F$ is nondifferentiable along the line segment $x x_{\mathrm{w}}$. So, the Hausdorff dimension of the set of nondifferentiability points of $f$ is less than or equal to $\operatorname{dim} M-1$ (because, if the dimension of nondifferntiability set of $f$ is bigger than $\operatorname{dim} M-1$, then the Hausdorff dimension of the set of nondifferentiability points of $F$ must be bigger than $\operatorname{dim} M-1+(n-\operatorname{dim} M)=n-1$, which is contradiction $)$.

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