# Existence of Positive Periodic Solutions of Fourth-order Singular $p$-Laplacian Neutral Functional Differential Equations 

Fanchao Kong ${ }^{\text {a }}$, Shiping Lu ${ }^{\text {b }}$<br>${ }^{a}$ Department of Mathematics, Hunan Normal University, Changsha, Hunan 410081, P. R. China<br>${ }^{b}$ College of Mathematics and Statistics, Nanjing University of Information Science and Technology, Nanjing 210044, P. R. China


#### Abstract

This work deals with the existence of positive periodic solutions for the fourth-order $p$-Laplacian neutral functional differential equations with a time-varying delay and a singularity. The results are established using the continuation theorem of coincidence degree theory and some analysis methods. A numerical example is presented to illustrate the effectiveness and feasibility of the proposed criterion.


## 1. Introduction

During the past several years, neutral functional differential equations have received more and more attention because of its widely applied backgrounds, for example population ecology, heat exchanges, mechanics and economics, see [6], [9], [10], [27]. In 1995, Zhang [30] studied the following linear and quasilinear neutral functional differential equations:

$$
(x(t)-b x(t-\tau))^{\prime}=-a x(t-r+\gamma h(t, x(t+\cdot)))+e(t)
$$

where $a, \tau, r$ are nonzero constants and $\gamma \in \mathbb{R}$ is a small parameter, $e \in C_{2 \pi}, h: \mathbb{R} \times C_{2 \pi}$ (real functions) $\rightarrow \mathbb{R}$ is continuous such that $h(t+2 \pi, \varphi) \equiv h(t, \varphi)$ on $\mathbb{R} \times C_{2 \pi}, C_{2 \pi}:=\{x \mid x \in C(\mathbb{R}, \mathbb{R}), x(t+2 \pi) \equiv x(t)\}$. Using some a priori estimation and the Leray-Schauder degree theory, the author obtained some existence theorems of periodic solutions.

On the basis of work of Zhang in [30], Lu in [12] discussed the the following first-order neutral functional differential equation

$$
\frac{d}{d t}(u(t)-k u(t-\tau))=g_{1}(u(t))+g_{2}\left(u\left(t-\tau_{1}\right)\right)+p(t)
$$

where $g_{1}, g_{2} \in C(\mathbb{R}, \mathbb{R}), p(t) \in C(\mathbb{R}, \mathbb{R})$ and $p(t+T) \equiv P(t), \tau, \tau_{1}, k$ are constants such that $|k| \neq 1$. By means of Mawhin's continuation theorem, existence criteria are established for the periodic solutions. Moreover, Lu in [13] gave some inequalities for $A$ :

If $|c|<1$ then $A$ has continuous inverse on $C_{T}$ and

[^0](1) $\left\|A^{-1} x\right\| \leq \frac{\|x\|_{0}}{|1-|c| l}, \forall x \in C_{T}$;
(2) $\int_{0}^{T}\left|\left(A^{-1} f\right)(t)\right| d t \leq \frac{1}{|1-|c|} \int_{0}^{T}|f(t)| d t, \forall f \in C_{T}$;
(3) $\int_{0}^{T}\left|A^{-1} f\right|^{2}(t) d t \leq \frac{1}{(1-|c|)^{2}} \int_{0}^{T} f^{2}(t) d t, \forall f \in C_{T}$.

After that, based on the work of Zhang and Lu, many authors further established the existence results of periodic solutions to different kinds of neutral functional differential equations, see [2], [8], [13], [14], [15], [16], [17], [21], [23], [24], [28] and the references therein. For example, in [24], Wang and Zhu studied a kind of fourth-order $p$-Laplacian neutral functional differential equation with a deviating argument in the form:

$$
\left(\varphi_{p}(x(t)-c x(t-\delta))^{\prime \prime}\right)^{\prime \prime}=f(x(t)) x^{\prime}(t)+g\left(t, x\left(t-\tau\left(t,|x|_{\infty}\right)\right)\right)+e(t)
$$

By means of Mawhin's continuation theorem, the existence results of periodic solutions are obtained.
In recent years, singular equations appear in a lot of physical models, see [18], [19], [20], [29] and the references therein. Different kinds of singular equations have been proposed by many authors, see for example [3], [4], [7], [22], [25], [26], [32] and the references therein.

However, to the best of our knowledge, there are few papers about the positive periodic solutions for the neutral functional differential equations with a singularity.

Recently, Kong and Lu in [11] study the existence of positive periodic for the following neutral Liénard differential equation with a singularity and a deviating argument

$$
((x(t)-c x(t-\sigma)))^{\prime \prime}+f(x(t)) x^{\prime}(t)+g(t, x(t-\delta))=e(t)
$$

where $c$ is a constant with $|c|<1,0 \leq \sigma, \delta<T, f: \mathbb{R} \rightarrow \mathbb{R}$ is continuous, $g:[0, T] \times(0,+\infty) \rightarrow \mathbb{R}$ is a continuous function and can be singular at $u=0 . e(t)$ is $T$-periodic with $\int_{0}^{T} e(t) d t=0$.

Inspired by the works mentioned above, in this paper, we consider the following fourth-order $p$ Laplacian neutral functional differential equation with a time-varying delay and a singularity

$$
\begin{equation*}
\left(\varphi_{p}(x(t)-c x(t-\delta))^{\prime \prime}\right)^{\prime \prime}+f(x(t)) x^{\prime}(t)+g(t, x(t-\delta(t)))=e(t) \tag{1.1}
\end{equation*}
$$

where $\varphi_{p}: \mathbb{R} \rightarrow \mathbb{R}, \varphi_{p}(u)=|u|^{p-2} u, p>1 ; c$ is a constant with $|c|<1, \delta$ is a continuous function; $f:(0,+\infty) \rightarrow \mathbb{R}$ is continuous; $g:[0, T] \times(0,+\infty) \rightarrow \mathbb{R}$ is a continuous function and can be singular at $u=0$; $e(t)$ is $T$-periodic with $\int_{0}^{T} e(t) d t=0$. By applying the continuation theorem of coincidence degree theory, we prove that Eq.(1.1) has at least one positive $T$-periodic solution.

Remark 1.1. The theorem and methods used to obtain the periodic solutions in [24] can be applied to the Eq.(1.1) if there is no singularity in Eq.(1.1). So, we extend the neutral functional differential equation to the singular case.

The rest of the paper is organized as follows. In Section 2, we state some necessary definitions and lemmas. In Section 3, we prove the main result. Finally, an example is given to support the effectiveness of our result in Section 4.

## 2. Preliminaries

Thought the paper, let

$$
C_{T}=\{\phi \in C(\mathbb{R}, \mathbb{R}), \phi(t+T) \equiv \phi(t)\}
$$

with the norm $|\phi|_{0}=\max _{t \in[0, T]}|\phi(t)|$,

$$
C_{T}^{1}=\left\{\phi \in C^{1}(\mathbb{R}, \mathbb{R}), \phi(t+T) \equiv \phi(t)\right\}
$$

with the norm $\|\phi\|=\max \left\{|\phi|_{0},\left|\phi^{\prime}\right|_{0}\right\}$.

Denote the operator A by

$$
\mathrm{A}: C_{T} \rightarrow C_{T},(\mathrm{~A} x)(t)=x(t)-c x(t-\sigma), \forall t \in \mathbb{R} .
$$

In order to use coincidence degree theory to study the existence of positive $T$-periodic solutions for 1.1, we rewrite 1.1) in the following form:

$$
\left\{\begin{array}{l}
(A u)^{\prime \prime}(t)=\varphi_{q}(v(t))  \tag{2.1}\\
v^{\prime \prime}(t)=-f(u(t)) u^{\prime}(t)-g(t, u(t-\delta(t)))+e(t)
\end{array}\right.
$$

where $q>1$ is a constant with $\frac{1}{p}+\frac{1}{q}=1$. Clearly, if $x(t)=(u(t), v(t))^{\top}$ is a $T$-periodic solution to system (2.1), then $u(t)$ must be a $T$-periodic solution of equation (1.1). Thus, the problem of finding a positive $T$-periodic solution for (1.1) reduces to finding one for (2.1).

Let

$$
\begin{aligned}
& X=\left\{x(t)=(u(t), v(t))^{\top} \in C^{2}\left(\mathbb{R}, \mathbb{R}^{2}\right), x(t) \equiv x(t+T)\right\} \\
& Y=\left\{x(t)=(u(t), v(t))^{\top} \in C^{2}\left(\mathbb{R}, \mathbb{R}^{2}\right), x(t) \equiv x(t+T)\right\}
\end{aligned}
$$

The normal $\|x\|=\max \left\{\left.|u|_{0, \mid} v\right|_{0}\right\}$, and $|u|_{0}=\max _{t \in[0, T]}|u|,|v|_{0}=\max _{t \in[0, T]}|v|$. It is obviously that $X$ and $Y$ are Banach spaces.

Define the operator

$$
\begin{equation*}
L: D(L) \subset X \rightarrow Y, \quad L x=x^{\prime \prime}=\left((\mathrm{A} u)^{\prime \prime}, v^{\prime \prime}\right)^{\top} \tag{2.2}
\end{equation*}
$$

where $D(L)=\left\{x(t)=(u(t), v(t))^{\top} \in C^{2}\left(\mathbb{R}, \mathbb{R}^{2}\right), x(t) \equiv x(t+T)\right\}$.
Define a nonlinear operator $N: D(N) \subset X \rightarrow Y$ as follows:

$$
\begin{equation*}
(N x)(t)=\binom{\varphi_{q}(v(t))}{-f(u(t)) u^{\prime}(t)-g(t, u(t-\delta(t)))+e(t)}, \forall t \in \mathbb{R} \tag{2.3}
\end{equation*}
$$

where $D(N)=\left\{x=(u, v)^{\top} \in X: u(t)>0, t \in[0, T]\right\}$. Then 2.1) can be converted to the abstract equation $L x=N x$.

From the definition of $L$, we can easily see that

$$
\operatorname{ker} L \cong \mathbb{R}^{2}, \quad \operatorname{Im} L=\left\{y \in Y, \int_{0}^{T} y(s) d s=0\right\}
$$

Thus $L$ is a Fredholm operator with index zero. Let the projections $P$ and $Q$ be

$$
\begin{aligned}
& P: X \rightarrow \operatorname{ker} L, \quad P x=\frac{1}{T} \int_{0}^{T} x(s) d s \\
& Q: Y \rightarrow \operatorname{Im} Q, \quad Q y=\frac{1}{T} \int_{0}^{T} y(s) d s
\end{aligned}
$$

Then we can see that $\operatorname{Im} P=\operatorname{ker} L$ and $\operatorname{ker} Q=\operatorname{Im} L$. Let $L_{p}=L_{D(L) \cap \operatorname{ker} P}$. We can easily prove that $L_{p}$ is invertible, $L_{p}^{-1}: \operatorname{Im} L \rightarrow D(L) \cap \operatorname{ker} P$, and

$$
\left(L_{p}^{-1} y\right)(t)=\int_{0}^{T} G(t, s) y(s) d s
$$

where $G(t, s)= \begin{cases}\frac{-s(T-t)}{-t}, & 0 \leq s \leq t \leq T ; \\ \frac{-t(T-s)}{T}, & s \leq t \leq s \leq T .\end{cases}$

Lemma 2.1. [14] If $|c| \neq 1$, then operator A has a unique continuous bounded inverse and satisfies the following conditions:
(1) $\int_{0}^{T}\left|\left[A^{-1} f\right](t)\right| d t \leq \frac{\int_{0}^{T}|f(t)| d t}{|1-|c||}, \forall f \in C_{T}$;
(2) $(A x)^{\prime \prime}=A^{\prime \prime} x, \forall x \in C_{T}^{2}:=\left\{x \in C^{2}(\mathbb{R}, \mathbb{R}), x(t+T) \equiv x(t)\right\}$.

Lemma 2.2. [5] Let $X$ and $Y$ be two real Banach spaces, $L: D(L) \subset X \rightarrow Y$ be a Fredholm operator with index zero, $\Omega \subset X$ be an open bounded set, and $N: \bar{\Omega} \subset X \rightarrow Y$ be L-compact on $\bar{\Omega}$. Suppose that all of the following conditions hold:
(1) $L x \neq \lambda N x, \forall x \in \partial \Omega \cap D(L), \forall \lambda \in(0,1)$;
(2) $Q N x \neq 0, \forall x \in \partial \Omega \cap \operatorname{ker} L$;
(3) $\operatorname{deg}\{J Q N, \Omega \cap \operatorname{ker} L, 0\} \neq 0$, where $J: \operatorname{Im} Q \rightarrow \operatorname{ker} L$ is an homeomorphism map. Then the equation $L x=N x$ has at least one solution on $D(L) \cap \bar{\Omega}$.

Lemma 2.3. 31] If $x \in C^{1}(\mathbb{R}, \mathbb{R})$ and $x(0)=x(T)=0$, then

$$
\int_{0}^{T}\left|x^{\prime}(t)\right|^{p} d t \leq\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t
$$

where $\pi_{p}=2 \int_{0}^{(p-1) / p} \frac{d s}{\left[1-s^{p} /(p-1)\right]^{1 / p}}=\frac{2 \pi(p-1)^{1 / p}}{p \sin (\pi / p)}$.
For the sake of convenience, we list the following assumptions:
[ $H_{1}$ ] There exist positive constants $D_{1}$ and $D_{2}$ with $D_{1}<D_{2}$ such that
(1) for each positive continuous $T$-periodic function $x(t)$ satisfying
$\int_{0}^{T} g(t, x(t)) d t=0$, then there exists a positive point $t_{0} \in[0, T]$
such that

$$
D_{1} \leq x\left(t_{0}\right) \leq D_{2}
$$

(2) $\bar{g}(x)<0$ for all $x \in\left(0, D_{1}\right)$ and $\bar{g}(x)>0$ for all $x>D_{2}$, where
$\bar{g}(x)=\frac{1}{T} \int_{0}^{T} g(t, x) d t, x>0$.
[ $H_{2}$ ] $g(t, x(t-\delta(t)))=g_{1}\left(t, x(t-\delta(t))+g_{0}(x(t))\right.$, where $g_{0}:(0,+\infty) \rightarrow \mathbb{R}$ is a continuous function,
$g_{1}:[0, T] \times(0,+\infty) \rightarrow \mathbb{R}$ is a continuous function and
(1) there exist positive constants $m_{0}$ and $m_{1}$ such that

$$
g(t, x) \leq m_{0} x^{p-1}+m_{1}, \text { for all }(t, x) \in[0, T] \times(0,+\infty) ;
$$

(2) $\int_{0}^{1} g_{0}(x) d x=-\infty$.
[ $H_{3}$ ] There exist positive constants $\alpha$ and $\beta$ such that

$$
F(x) \leq \alpha x^{p-1}+\beta, \text { for all } x \in(0,+\infty)
$$

where $F(x)=\int_{0}^{x} f(s) d s$.

## 3. Main Results

Theorem 3.1. Suppose that conditions $\left[H_{1}\right]-\left[H_{3}\right]$ hold and

$$
\frac{\left[2(1+|c|) m_{0}+\alpha|c|\right] T^{2 p-1}}{\pi_{p}^{p}\left|1-|c|^{p}\right.}<1
$$

then there exist positive constants $A_{1}, A_{2}, A_{3}$ and $\rho$, which are independent of $\lambda$ such that

$$
A_{1} \leq u(t) \leq A_{2}, \quad\left|u^{\prime}\right|_{0} \leq A_{3},|v|_{0} \leq \rho,
$$

where $u(t)$ is any solution to the equation $L x=\lambda N x, \lambda \in(0,1]$.
Proof Consider the following operator equation

$$
L x=\lambda N x, \lambda \in(0,1)
$$

where $L$ and $N$ are defined by $(2.2)$ and (2.3), respectively. Let

$$
\Omega_{1}=\left\{(u, v)^{\top} \in X: \min _{t \in[0, T]} u(t)>0, L x=\lambda N x, \lambda \in(0,1)\right\} .
$$

If $x=(u, v)^{\top} \in \Omega_{1}$, then $(u, v)$ satisfies

$$
\left\{\begin{array}{l}
(\mathrm{A} u)^{\prime \prime}(t)=\lambda \varphi_{q}(v(t))  \tag{3.1}\\
v^{\prime \prime}(t)=-\lambda f(u(t)) u^{\prime}(t)-\lambda g(t, u(t-\delta(t)))+\lambda e(t)
\end{array}\right.
$$

From the first equation of (3.1), we can get $v(t)=\lambda^{-1}(\mathrm{~A} u)^{\prime \prime}(t)$, which combining with the second equation of (3.1) yields

$$
\begin{equation*}
\left(\varphi_{p}\left((A u)^{\prime \prime}(t)\right)\right)^{\prime \prime}+\lambda^{p} f(u(t)) u^{\prime}(t)+\lambda^{p} g(t, u(t-\delta(t)))=\lambda^{p} e(t) \tag{3.2}
\end{equation*}
$$

Integrating the equation (3.2) on the interval [ $0, T$ ], we have

$$
\int_{0}^{T}\left(\varphi_{p}\left((A u)^{\prime \prime}(t)\right)\right)^{\prime \prime} d t+\lambda^{p} \int_{0}^{T} f(u(t)) u^{\prime}(t) d t+\lambda^{p} \int_{0}^{T} g(t, u(t-\delta(t))) d t=\lambda^{p} \int_{0}^{T} e(t) d t
$$

then we can have

$$
\begin{equation*}
\int_{0}^{T} g(t, u(t-\delta(t))) d t=0 \tag{3.3}
\end{equation*}
$$

It follows from $\left[H_{1}\right](1)$ that there exist positive constants $D_{1}, D_{2}$ and $t_{0} \in[0, T]$ such that

$$
\begin{equation*}
D_{1} \leq u\left(t_{0}\right) \leq D_{2} \tag{3.4}
\end{equation*}
$$

From this, we obtain

$$
\begin{equation*}
|u|_{0}=\max _{t \in[0, T]}|u(t)| \leq \max _{t \in[0, T]}\left|u\left(t_{0}\right)+\int_{t_{0}}^{t} u^{\prime}(s) d s\right| \leq D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s, \tag{3.5}
\end{equation*}
$$

Multiplying the both sides of 3.2 by $(A u)(t)$ and integrating on the interval [0,T], we get

$$
\begin{aligned}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t= & \lambda^{p} \int_{0}^{T} f(u(t)) u^{\prime}(t)(\mathrm{A} u)(t) d t+\lambda^{p} \int_{0}^{T} g(t, u(t-\delta(t)))(\mathrm{A} u)(t) d t \\
& -\lambda^{p} \int_{0}^{T} e(t)(\mathrm{A} u)(t) d t \\
\leq & \left|\int_{0}^{T} f(u(t)) u^{\prime}(t)[u(t)-c u(t-\sigma)] d t\right| \\
& +(1+|c|)|u|_{0} \int_{0}^{T}|g(t, u(t-\delta(t)))| d t+(1+|c|)|u|_{0} \int_{0}^{T}|e(t)| d t \\
= & \left|\int_{0}^{T}\left[f(u(t)) u^{\prime}(t) u(t)-c f(u(t)) u^{\prime}(t) u(t-\sigma)\right] d t\right| \\
& +(1+|c|)|u|_{0} \int_{0}^{T}|g(t, u(t-\delta(t)))| d t+(1+|c|)|u|_{0} \int_{0}^{T}|e(t)| d t \\
= & |c|\left|\int_{0}^{T} F(u(t)) u^{\prime}(t-\sigma) d t\right|+(1+|c|)|u|_{0} \int_{0}^{T}|g(t, u(t-\delta(t)))| d t \\
& +(1+|c|)|u|_{0} \int_{0}^{T}|e(t)| d t \\
\leq & |c| \int_{0}^{T}|F(u(t))|\left|u^{\prime}(t-\sigma)\right| d t+(1+|c|)|u|_{0} \int_{0}^{T}|g(t, u(t-\delta(t)))| d t \\
& +(1+|c|)|u|_{0} \int_{0}^{T}|e(t)| d t,
\end{aligned}
$$

which combining with $\left[\mathrm{H}_{3}\right]$ yields

$$
\begin{align*}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq & \alpha|c||u|_{0}^{p-1} \int_{0}^{T}\left|u^{\prime}(t-\sigma)\right| d t+\beta|c| \int_{0}^{T}\left|u^{\prime}(t-\sigma)\right| d t \\
& +(1+|c|)|u|_{0} \int_{0}^{T}|g(t, u(t-\delta(t)))| d t  \tag{3.6}\\
& +(1+|c|)|u|_{0}|e|_{0} T
\end{align*}
$$

Write

$$
\begin{aligned}
& E_{+}=\{t \in[0, T]: g(t, u(t-\delta(t))) \geq 0\} \\
& E_{-}=\{t \in[0, T]: g(t, u(t-\delta(t))) \leq 0\}
\end{aligned}
$$

Then it follows from 3.3) and $\left[H_{2}\right](1)$ that

$$
\begin{align*}
\int_{0}^{T}|g(t, u(t-\delta(t)))| d t & =\int_{E_{+}} g(t, u(t-\delta(t))) d t-\int_{E_{-}} g(t, u(t-\delta(t))) d t \\
& =2 \int_{E_{+}} g(t, u(t-\delta(t))) d t  \tag{3.7}\\
& \leq 2 m_{0} \int_{0}^{T} u^{p-1}(t-\delta(t)) d t+2 \int_{0}^{T} m_{1} d t \\
& \leq 2 m_{0} T|u|_{0}^{p-1}+2 T m_{1} .
\end{align*}
$$

Substituting (3.7) into (3.6), combining with (3.5), we can have

$$
\begin{align*}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq & 2(1+|c|) m_{0} T|u|_{0}^{p}+\alpha|c||u|_{0}^{p-1} \int_{0}^{T}\left|u^{\prime}(t-\sigma)\right| d t \\
& +\beta|c| \int_{0}^{T}\left|u^{\prime}(t-\sigma)\right| d t+2(1+|c|) m_{1} T|u|_{0}+(1+|c|)|e|_{0} T|u|_{0} \\
\leq & 2(1+|c|) m_{0} T\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)^{p}  \tag{3.8}\\
& +\alpha|c|\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)^{p-1} \int_{0}^{T}\left|u^{\prime}(t)\right| d t \\
& +\beta|c| \int_{0}^{T}\left|u^{\prime}(t)\right| d t+2(1+|c|) m_{1} T\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right) \\
& +(1+|c|)|e|_{0} T\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)
\end{align*}
$$

Moreover,

$$
\begin{equation*}
\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)^{p}=\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p}\left(1+\frac{D_{2}}{\int_{0}^{T}\left|u^{\prime}(t)\right| d t}\right)^{p} . \tag{3.9}
\end{equation*}
$$

By classical elementary inequalities, we see that there exists a $l(p)>0$ which is dependent on $p$ only, such that

$$
\begin{equation*}
(1+x)^{p}<1+(1+p) x, \quad x \in(0, l(p)] . \tag{3.10}
\end{equation*}
$$

Then, from 3.9 we should consider the following two cases:
Case 1. $\frac{D_{2}}{\int_{0}^{T}\left|u^{\prime}(t)\right| d t}>l(p)$, then $\int_{0}^{T}\left|u^{\prime}(t)\right| d t<\frac{D_{2}}{l(p)}$ and from 3.5, we have

$$
\begin{equation*}
|u|_{0}<D_{2}+\frac{D_{2}}{l(p)}:=M_{0} \tag{3.11}
\end{equation*}
$$

Case 2. $\frac{D_{2}}{\int_{0}^{T}\left|u^{\prime}(t)\right| d t} \leq l(p)$, then it follows from (3.9) and (3.10) that

$$
\begin{align*}
\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)^{p} & =\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p}\left(1+\frac{D_{2}}{\int_{0}^{T}\left|u^{\prime}(t)\right| d t}\right)^{p} \\
& \leq\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p}\left(1+\frac{D_{2}(p+1)}{\int_{0}^{T}\left|u^{\prime}(t)\right| d t}\right)^{p}  \tag{3.12}\\
& =\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p}+D_{2}(p+1)\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p-1}
\end{align*}
$$

Substituting (3.12) into (3.8), we see that

$$
\begin{align*}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq & 2(1+|c|) m_{0} T\left[\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p}+D_{2}(p+1)\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p-1}\right] \\
& +\alpha|c|\left[\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p-1}+D_{2}(p+1)\left(\int_{0}^{T}\left|u^{\prime}(t)\right| d t\right)^{p-2}\right] \cdot \int_{0}^{T}\left|u^{\prime}(t)\right| d t \\
& +\beta|c| \int_{0}^{T}\left|u^{\prime}(t)\right| d t+2(1+|c|) m_{1} T\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)  \tag{3.13}\\
& +(1+|c|)|e|_{0} T\left(D_{2}+\int_{0}^{T}\left|u^{\prime}(s)\right| d s\right)
\end{align*}
$$

which together with the Hölder inequality and Lemma 2.3 yields

$$
\begin{aligned}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq & \frac{\left[2(1+|c|) m_{0}+\alpha|c|\right] T^{2 p-1}}{\pi_{p}^{p}} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t \\
& +\left[2(1+|c|) m_{0} T+\alpha|c|\right] D_{2}(p+1) T^{\frac{(p-1)^{2}}{p}}\left[\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t\right]^{\frac{p-1}{p}} \\
& +\left[\beta|c|+2(1+|c|) m_{1} T+(1+|c|)|e|_{0} T\right] T^{\frac{p-1}{p}}\left[\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t\right]^{\frac{1}{p}} \\
& +\left[2 m_{1}+\mid e_{0}\right](1+|c|) T D_{2} .
\end{aligned}
$$

Furthermore, by applying Lemma 2.1. we can obtain

$$
\begin{aligned}
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq & \frac{\left[2(1+|c|) m_{0}+\alpha|c|\right] T^{2 p-1}}{\pi_{p}^{p}|1-|c||^{p}} \int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \\
& +\left[2(1+|c|) m_{0} T+\alpha|c|\right] D_{2}(p+1) T^{\frac{(p-1)^{2}}{p}}\left[\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t\right]^{\frac{p-1}{p}} \\
& +\left[\beta|c|+2(1+|c|) m_{1} T+(1+|c|)|e|_{0} T\right] T^{\frac{p-1}{p}}\left[\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|x^{\prime \prime}(t)\right|^{p} d t\right]^{\frac{1}{p}} \\
& +\left[2 m_{1}+|e|_{0}\right](1+|c|) T D_{2} .
\end{aligned}
$$

It follows from $\frac{\left[2(1+|c|) m_{0}+\alpha|c| T^{2 p-1}\right.}{\pi_{p}^{p}|1-|c||^{p}}<1$ that there exists a positive constant $M_{1}>0$ such that

$$
\int_{0}^{T}\left|(\mathrm{~A} u)^{\prime \prime}(t)\right|^{p} d t \leq M_{1}
$$

Then by Lemma 2.1. we can see that

$$
\begin{equation*}
\int_{0}^{T}\left|u^{\prime \prime}(t)\right|^{p} d t \leq \frac{M_{1}}{\left|1-|c|^{p}\right.}:=M_{2} \tag{3.14}
\end{equation*}
$$

which together with (3.5) and Lemma 2.3 yields

$$
\begin{aligned}
|u|_{0} & \leq D_{2}+T^{\frac{p-1}{p}}\left(\int_{0}^{T}\left|u^{\prime}(t)\right|^{p} d t\right)^{\frac{1}{p}} \\
& \leq D_{2}+T^{\frac{p-1}{p}}\left[\left(\frac{T}{\pi_{p}}\right)^{p} \int_{0}^{T}\left|u^{\prime \prime}(t)\right|^{p} d t\right]^{\frac{1}{p}} \\
& \leq D_{2}+\frac{T^{2 p-1} M_{2}^{\frac{1}{p}}}{\pi_{p}}:=M_{3}
\end{aligned}
$$

Therefore, in both Case 1 and Case 2, we can conclude that

$$
\begin{equation*}
|u|_{0} \leq M_{3} \tag{3.15}
\end{equation*}
$$

Moreover, since $u(t)$ is $T$-periodic, there exists a point $t_{0} \in[0, T]$ such that $u^{\prime}\left(t_{0}\right)=0$. Then by applying Hölder's inequality and in view of (3.14), we have

$$
\begin{aligned}
\left|u^{\prime}\right|_{0} & \leq \int_{0}^{T}\left|u^{\prime \prime}(t)\right| d t \\
& \leq T^{\frac{1}{p}}\left(\int_{0}^{T}\left|u^{\prime \prime}(t)\right|^{p} d t\right)^{1 / p} \\
& \leq T^{\frac{1}{p}} M_{2}^{\frac{1}{p}}:=A_{3}
\end{aligned}
$$

From the second equation of 3.1, we can get

$$
\int_{0}^{T}\left|v^{\prime \prime}(t)\right| d t \leq \int_{0}^{T}\left|f(u(t)) \| u^{\prime}(t)\right| d t+\lambda \int_{0}^{T}|g(t, u(t-\delta(t)))| d t+\lambda \int_{0}^{T}|e(t)| d t
$$

Set $f_{M_{3}}=\max _{|u|<M_{3}}|f(u(t))|$, then by 3.7 we have

$$
\int_{0}^{T}\left|v^{\prime \prime}(t)\right| d t \leq \lambda\left[f_{M_{3}} T\left|u^{\prime}\right|_{0}+2 m_{0} T|u|_{0}^{p-1}+2 T m_{1}+|e|_{0} T\right],
$$

in view of 3.15 and (3.16), we get

$$
\begin{equation*}
\int_{0}^{T}\left|v^{\prime \prime}(t)\right| d t \leq \lambda\left[f_{M_{3}} T A_{3}+2 m_{0} T M_{3}^{p-1}+2 T m_{1}+|e|_{0} T\right] \tag{3.17}
\end{equation*}
$$

Moreover, integrating the first equation of (3.1) on the interval [ $0, T$ ], we have

$$
\int_{0}^{T} u^{\prime \prime}(t) d t=\int_{0}^{T}\left(A^{-1} v\right)(t) d t=0
$$

which implies that there exists $\eta \in[0, T]$ such that $v(\eta)=0$. Thus,

$$
|v(t)|=\left|\int_{\eta}^{t} v^{\prime}(s) d s+v(\eta)\right| \leq \int_{0}^{T}\left|v^{\prime}(s)\right| d s \leq \sqrt{T}\left(\int_{0}^{T}\left|v^{\prime}(s)\right|^{2} d s\right)^{1 / 2}
$$

which together with Lemma 2.3 and (3.14) gives

$$
\begin{align*}
|v|_{0} & \leq \sqrt{T}\left(\int_{0}^{T}\left|v^{\prime}(s)\right|^{2} d s\right)^{1 / 2} \cdot \frac{T \sqrt{T}}{\pi} \cdot\left(\int_{0}^{T}\left|v^{\prime \prime}(s)\right|^{2} d s\right)^{1 / 2} \\
& \leq \frac{T^{2}}{\pi}\left(f_{M_{3}} T A_{3}+2 m_{0} T M_{3}^{p-1}+2 T m_{1}+|e|_{0} T\right)^{1 / 2}  \tag{3.18}\\
& :=\rho
\end{align*}
$$

On the other hand, it follows from the second equation of 3.1) and [ $\mathrm{H}_{2}$ ] that

$$
\begin{equation*}
v^{\prime \prime}(t)=-\lambda f(u(t)) u^{\prime}(t)-\lambda\left[g_{1}(t, u(t-\delta(t)))+g_{0}(u(t))\right]+\lambda e(t) . \tag{3.19}
\end{equation*}
$$

Multiplying both sides of Eq. 3.19 by $u^{\prime}(t)$, we have

$$
\begin{equation*}
v^{\prime \prime}(t) u^{\prime}(t)=-\lambda f(u(t)) u^{\prime}(t) u^{\prime}(t)-\lambda\left[g_{1}(t, u(t-\delta(t)))+g_{0}(u(t))\right] u^{\prime}(t)+\lambda e(t) u^{\prime}(t) . \tag{3.20}
\end{equation*}
$$

Let $t_{0} \in[0, T]$ be as in 3.4. For any $t \in\left[t_{0}, T\right]$, integrating Eq. 3.20) on the interval $\left[t_{0}, T\right]$, we can get

$$
\begin{aligned}
\lambda \int_{u\left(t_{0}\right)}^{u(t)} g_{0}(u) d u= & \lambda \int_{t_{0}}^{t} g_{0}(u(t)) u^{\prime}(t) d t \\
= & -\int_{t_{0}}^{t} v^{\prime \prime}(t) u^{\prime}(t) d t-\lambda \int_{t_{0}}^{t} f(u(t)) u^{\prime}(t) u^{\prime}(t) d t \\
& -\lambda \int_{t_{0}}^{t} g_{1}(t, u(t-\delta(t))) u^{\prime}(t) d t+\lambda \int_{t_{0}}^{t} e(t) u^{\prime}(t) d t
\end{aligned}
$$

which together with (3.17) yields

$$
\begin{aligned}
\lambda\left|\int_{u\left(t_{0}\right)}^{u(t)} g_{0}(u) d u\right|= & \lambda\left|\int_{t_{0}}^{t} g_{0}(u(t)) u^{\prime}(t) d t\right| \\
\leq & \int_{0}^{T}\left|v^{\prime \prime}(t)\right|\left|u^{\prime}(t)\right| d t+\lambda \int_{0}^{T}|f(u(t))| u^{\prime}(t)| | u^{\prime}(t) \mid d t \\
& +\lambda \int_{0}^{T}\left|g_{1}(t, u(t-\delta(t)))\right| \| u^{\prime}(t)\left|d t+\lambda \int_{0}^{T}\right| e(t)| | u^{\prime}(t) \mid d t \\
\leq & \lambda\left|u^{\prime}\right|_{0}\left[f_{M_{3}} T A_{3}+2 m_{0} T M_{3}^{p-1}+2 T m_{1}+|e|_{0} T\right] \\
& +\lambda\left|u^{\prime}\right|_{0}^{2} f_{M_{3}} T+\lambda\left|u^{\prime}\right|_{0} \int_{0}^{T}\left|g_{1}(t+\delta(t), u(t))\right| d t \\
& +\lambda\left|u^{\prime}\right|_{0} \int_{0}^{T}|e(t+\delta(t))| d t .
\end{aligned}
$$

Set $g_{M_{3}}=\max _{t \in[0, T],|u| \leq M_{3}}\left|g_{1}(t, u)\right|$, then we have

$$
\begin{aligned}
\left|\int_{u\left(t_{0}\right)}^{u(t)} g_{0}(u) d u\right| \leq & \left|u^{\prime}\right|_{0}\left[f_{M_{3}} T A_{3}+2 m_{0} T M_{3}^{p-1}+2 T m_{1}+|e|_{0} T\right] \\
& +\left|u^{\prime}\right|_{0}^{2} T f_{M_{3}}+\left|u^{\prime}\right|_{0} T g_{M_{3}}+\left|u^{\prime}\right|_{0} T \mid e_{0}
\end{aligned}
$$

which combining with 3.16 gives

$$
\begin{aligned}
\left|\int_{u\left(t_{0}\right)}^{u(t)} g_{0}(u) d u\right| \leq & A_{3}\left[f_{M_{3}} T A_{3}+2 m_{0} T M_{3}^{p-1}+2 T m_{1}+|e|_{0} T\right] \\
& +A_{3}^{2} T f_{M_{3}}+T A_{3} g_{M_{3}}+T A_{3}|e|_{0} \\
< & +\infty
\end{aligned}
$$

According to condition (2) in $\left[H_{2}\right]$, we can see that there exists a constant $M_{4}>0$ such that, for $t \in\left[t_{0}, T\right]$,

$$
\begin{equation*}
u(t) \geq M_{4} . \tag{3.21}
\end{equation*}
$$

For the case $t \in\left[0, t_{0}\right]$, we can handle similarly.
Let us define

$$
0<A_{1}=\min \left\{D_{1}, M_{3}\right\}
$$

and

$$
A_{2}=\max \left\{D_{2}, M_{4}\right\}
$$

Then by (3.4, 3.15) and (3.21), we can obtain

$$
\begin{equation*}
A_{1} \leq u(t) \leq A_{2} \tag{3.22}
\end{equation*}
$$

Clearly, $A_{1}$ and $A_{2}$ are independent of $\lambda$. Therefore, from (3.16, 3.18) and (3.22), we can see that the proof of Theorem 3.1 is now complete.

Theorem 3.2. Suppose that all the conditions in Theorem 3.1 hold, then system (2.1) has at least one positive T-periodic solution $(u, v)^{\top} \subset \Omega_{1}$ such that

$$
A_{1} \leq u(t) \leq A_{2},\left|u^{\prime}\right|_{0} \leq A_{3},|v|_{0} \leq \rho
$$

Proof Set

$$
\Omega=\left\{x=(u, v)^{\top} \in X: \frac{A_{1}}{2}<u(t)<A_{2}+1,\left|u^{\prime}\right|_{0}<A_{3}+1,|v|_{0}<\rho+1\right\}
$$

then condition (1) of Lemma 2.2 is satisfied.
Suppose that there exists $x=(u, v)^{\top} \in \partial \Omega \cap \operatorname{ker} L$ such that

$$
Q N x=\frac{1}{T} \int_{0}^{T} N x(s) d s=(0,0)^{\top}
$$

then $u \in \mathbb{R}$ and $v \in \mathbb{R}$ are constant valued functions and satisfy

$$
\left\{\begin{array}{l}
\frac{1}{T} \int_{0}^{T}\left[\mathrm{~A}^{-1}(v)\right] d t=0  \tag{3.23}\\
\frac{1}{T} \int_{0}^{T}\left[-f(u) u^{\prime}-g(t, u)+e(t)\right] d t=0
\end{array}\right.
$$

It follows from condition (1) in $\left[H_{1}\right]$ and the second part of Lemma 2.2 that

$$
\frac{A_{1}}{2}<D_{1} \leq u \leq D_{2}<A_{2}+1, v=0
$$

which contradicts the assumption $x \in \partial \Omega$. This contradiction implies that condition (2) of Lemma 2.2 is satisfied.

Finally, we will show that condition (3) of Lemma 2.2 is also satisfied.
Let

$$
z=K x=K\binom{u}{v}=\binom{u-\frac{A_{1}+A_{2}}{2}}{v}
$$

then, we have

$$
x=z+\binom{\frac{A_{1}+A_{2}}{2}}{0} .
$$

Define $J: \operatorname{Im} Q \rightarrow \operatorname{ker} L$ is a linear isomorphism of the form

$$
J(u, v)=\binom{-v}{u} .
$$

Moreover, define

$$
H(\mu, x)=\mu K x+(1-\mu) J Q N x, \quad \forall(x, \mu) \in(\Omega \cap \operatorname{ker} L) \times[0,1]
$$

Then,

$$
\begin{equation*}
H(\mu, x)=\binom{\mu u-\frac{\mu\left(A_{1}+A_{2}\right)}{2}}{\mu v}+\frac{1-\mu}{T}\binom{\int_{0}^{T}\left[f(u) u^{\prime}+g(t, u)\right] d t}{\int_{0}^{T} \varphi_{q}(v) d t} \tag{3.24}
\end{equation*}
$$

Now we claim that $H(\mu, x)$ is a homotopic mapping. Assume, by way of contradiction, i.e., there exists $\mu_{0} \in[0,1]$ and $x_{0}=\binom{u_{0}}{v_{0}} \in \partial(\Omega \cap \operatorname{ker} L)$ such that $H\left(\mu_{0}, x_{0}\right)=0$.
Substituting $\mu_{0}$ and $x_{0}$ into (3.21), we have

$$
\begin{equation*}
H\left(\mu_{0}, x_{0}\right)=\binom{\mu_{0} u_{0}-\frac{\mu_{0}\left(A_{1}+A_{2}\right)}{2}+\left(1-\mu_{0}\right) f\left(u_{0}\right) u_{0}^{\prime}+\left(1-\mu_{0}\right) \bar{g}\left(u_{0}\right)}{\mu_{0} v_{0}+\left(1-\mu_{0}\right) \varphi_{q}\left(v_{0}\right)} \tag{3.25}
\end{equation*}
$$

It follows $H\left(\mu_{0}, x_{0}\right)=0$ that

$$
\mu_{0} v_{0}+\left(1-\mu_{0}\right) \varphi_{q}\left(v_{0}\right)=0,
$$

which together with $\mu_{0} \in[0,1]$ yields $v_{0}=0$. Thus, $u_{0}=\frac{A_{1}}{2}$ or $u_{0}=A_{2}+1$.
Furthermore,
If $u_{0}=\frac{A_{1}}{2}$, it follows from $\left[H_{1}\right](2)$ that $\bar{g}\left(u_{0}\right)<0$, then substituting $u_{0}=\frac{A_{1}}{2}$ and $v_{0}=0$ into (3.25), we have

$$
\begin{aligned}
& \frac{\mu_{0} A_{1}}{2}-\frac{\mu_{0}\left(A_{1}+A_{2}\right)}{2}+\left(1-\mu_{0}\right) \bar{g}\left(\frac{A_{1}}{2}\right) \\
& =-\frac{\mu_{0} A_{2}}{2}+\left(1-\mu_{0}\right) \bar{g}\left(\frac{A_{1}}{2}\right) \\
& <0
\end{aligned}
$$

If $u_{0}=A_{2}+1$, it follows from $\left[H_{1}\right](2)$ that $\bar{g}\left(u_{0}\right)>0$, then substituting $u_{0}=A_{2}+1$ and $v_{0}=0$ into 3.22 , we have

$$
\begin{aligned}
& \mu_{0}\left(A_{2}+1\right)-\frac{\mu_{0}\left(A_{1}+A_{2}\right)}{2}+\left(1-\mu_{0}\right) \bar{g}\left(A_{2}+1\right) \\
& =\frac{\mu_{0}\left(A_{2}-A_{1}+2\right)}{2}+\left(1-\mu_{0}\right) \bar{g}\left(A_{2}+1\right) \\
& >0
\end{aligned}
$$

From (3.26) and 3.27, we can see that $H\left(\mu_{0}, x_{0}\right) \neq 0$, which contradicts the assumption. Therefore $H(\mu, x)$ is a homotopic mapping and $x^{\top} H(\mu, x) \neq 0$. Moreover, for all $(x, \mu) \in(\partial \Omega \cap \operatorname{ker} L) \times[0,1]$, we have

$$
\begin{aligned}
\operatorname{deg}(J Q N, \Omega \cap \operatorname{ker} L, 0) & =\operatorname{deg}(H(0, x), \Omega \cap \operatorname{ker} L, 0) \\
& =\operatorname{deg}(H(1, x), \Omega \cap \operatorname{ker} L, 0) \\
& =\operatorname{deg}(K x, \Omega \cap \operatorname{ker} L, 0) \\
& =\sum_{x \in K^{-1}(0)} \operatorname{sgn}\left(\operatorname{det} K^{\prime}(x)\right) \\
& =1 \neq 0 .
\end{aligned}
$$

Thus, the condition (3) of Lemma 2.2 is also satisfied. Therefore, by applying Lemma 2.2, we can see that 2.1) has a positive $T$-periodic solution $(u, v)^{\top} \subset \bar{\Omega}$. Clearly, $u$ is a positive $T$-periodic solution to (1.1), and $(u, v)^{\top}$ must be in $\Omega_{1}$ for the case of $\lambda=1$. Thus, by using Theorem 3.1. we have

$$
A_{1} \leq u(t) \leq A_{2},\left|u^{\prime}\right|_{0} \leq A_{3},|v|_{0} \leq \rho
$$

Hence, we can conclude that Eq. (1.1) has at least one positive $T$-periodic solution.

## 4. Example

In this section, we provide an example to illustrate our main result.
Example 4.1. Consider the following fourth-order p-Laplacian neutral functional differential equation with a timevarying delay and a singularity:

$$
\begin{equation*}
\left(\varphi_{4}\left(x(t)-\frac{1}{2} x\left(t-\frac{\pi}{8}\right)\right)^{\prime \prime}\right)^{\prime \prime}+\left(2 \sin u(t)+\frac{1}{4}\right) u^{\prime}(t)+\frac{1}{64}(1+\sin 6 t) u(t-\cos 6 t)-\frac{1}{u(t-\cos 6 t)}=\sin 6 t \tag{4.1}
\end{equation*}
$$

Conclusion: The Problem (4.1) has at least one positive $\pi / 3$-periodic solution.
Proof. Corresponding to (1.1), we have

$$
\begin{gathered}
f(u(t))=2 \sin u(t)+\frac{1}{4}, e(t)=\sin 6 t, \delta(t)=\cos 6 t \\
g(t, u(t-\delta(t)))=\frac{1}{64}(1+\sin 6 t) u(t-\cos 6 t)-\frac{1}{u(t-\cos 6 t)}
\end{gathered}
$$

Then, we can have and choose

$$
p=4, T=\frac{\pi}{3}, c=\frac{1}{2}, m_{0}=\frac{1}{32}, \alpha=\frac{1}{4}, D_{1}=1, D_{2}=9 .
$$

It is easy to see that $\left[H_{1}\right]-\left[H_{3}\right]$ hold. Moreover, we also have $\pi_{4}=\frac{2 \pi 3^{1 / 4}}{4 \sin (\pi / 4)}=\frac{3^{1 / 4} \pi}{\sqrt{2}}$,

$$
\frac{\left[2(1+|c|) m_{0}+\alpha|c|\right] T^{2 p-1}}{\pi_{p}^{p}\left|1-|c|^{p}\right.} \approx 0.0662<1
$$

which implies that Theorem 3.1 is satisfied. Therefore, by Theorem 3.2 we can see that Eq. 4.1 has at least one positive $\pi / 3$-periodic solution.

## References

[1] M. Abbas, D. Ilić, Common fixed points of generalized almost nonexpansive mappings, Filomat 24 (2010) 11-18.
[2] A. Ardjouni, A. Rezaiguia, A. Djoudi, Existence of positive periodic solutions for fourth-order nonlinear neutral differential equations with variable delay, Advance in nonlinear analysis 3 (2014) 157-163.
[3] A. Fonda, R. Toader, Periodic orbits of radially symmetric Keplerianlike systems: A topological degree approach, Journal of Differential Equations 244 (2008) 3235-3264.
[4] D. Franco, P. J. Torres, Periodic solutions of singular systems without the strong force condition, Proceedings of the american mathematical society 136 (2008) 1229-1236.
[5] R. E. Gaines, J. L. Mawhin, Coincidence Degree and Nonlinear Differential Equations, Lecture Notes in Mathematics, Springer, Berlin, 1977.
[6] J. Hale, Theory of Functional Differential Equations, Springer, New York, 1977.
[7] R. Hakl, P. J. Torres, On periodic solutions of second-order differential equations with attractive-repulsive singularities, Journal of Differential Equations 248 (2010) 111-126.
[8] Z. M. He, B. Du, Periodic solutions for a kind of neutral functional differential systems, Boundary Value Problems 2014 (2014) 151.
[9] Y. Kuang, Delay Differential Equations with Applications in Population Dynamics, Academic Press, New York, 1993.
[10] V. Kolmannovskii, A. Myshkis, Introduction to the Theory and Applications of Functional Differential Equations, Kluwer Academic, London, 1999.
[11] F. C. Kong, S. P. Lu, Z. T. Liang, Existence of positive periodic solutions for a kind of neutral liénard differential equation with a singularity, Electronic Journal of Differential Equations 242 (2015) 1-12.
[12] S. P. Lu, W. G. Ge, On the existence of periodic solutions for neutral functional diffierential equation, Nonlinear Analysis 54 (2003) 1285-1306.
[13] S. P. Lu, W. G. Ge, Existence of periodic solutions for a kind of second-order neutral functional differential equation, Applied Mathematics and Computation 157 (2004) 433-448.
[14] S. P. Lu, W. G. Ge, Z. X. Zheng, Periodic solutions to neutral differential equation with deviating arguments, Applied Mathematics and Computation 152 (2004) 17-27.
[15] Z. X. Li, X. Wang, Existence of positive periodic solutions for neutral functional differential equations, Electronic Journal of Differential Equations 34 (2006) 1-8.
[16] Y. Luo, W. B. Wang, J. H. Shen, Existence of positive periodic solutions for two kinds of neutral functional differential equations, Applied Mathematics Letters 21 (2008) 581-587.
[17] Z. G. Luo, L. P. Luo, Y. H. Zeng, Positive Periodic Solution for the Generalized Neutral Differential Equation with Multiple Delays and Impulse, Journal of Applied Mathematics 2014 (2014), Art. 592513, 12pp.
[18] J. J. Mawhin, Topological degree and boundary value problems for nonlinear differential equations, In: Furi, M., Zecca, P. (eds.) Topologic Methods for Ordinary Differential Equations. Lecture Notes in Mathematics, vol. 1537. Springer, New York, 1993.
[19] H. H. Pishkenari, M. Behzad, A. Meghdari, Nonlinear dynamic analysis of atomic force microscopy under deterministic and random excitation, Chaos, Solitons and Fractals 37 (2008) 748-762.
[20] S. Rützel, S. Lee and A. Raman, Nonlinear dynamics of atomic-force-microscope probes driven in Lennard-Jones potentials, Proceedings of the Royal Society A-Mathematical Physical and Engineering Science 459 (2003) 1925-1948.
[21] J. H. Shen, R. X. Liang, Periodic solutions for a kind of second order neutral functional differential equations, Applied Mathematics and Computation 190 (2007) 1394-1401.
[22] Z. H. Wang, Periodic solutions of the second order differential equations with singularities, Nonlinear Analysis: Theory, Methods and Applications 58 (2004) 319-331.
[23] J. Wu, Z. C. Wang, Two periodic solutions of second-order neutral functional differential equations, Journal of Mathematical Analysis and Applications 329 (2007) 677-689.
[24] K. Wang, Y. L. Zhu, Periodic solutions for a fourth-order $p$-Laplacian neutral functional differential equation, Journal of The Franklin Institute 347 (2010) 1158-1170.
[25] Z. H. Wang, T. T. Ma, Existence and multiplicity of periodic solutions of semilinear resonant Duffing equations with singularities, Nonlinearity 25 (2012) 279-307.
[26] Z. H. Wang, Periodic solutions of Liénard equation with a singularity and a deviating argument, Nonlinear Analysis: Real World Applications 16 (2014) 227-234.
[27] S. Y. Xu, J. Lam, Y. Zou, Further results on delay-dependent robust stability conditions of uncertain neutral systems, International Journal of Robust and Nonlinear Control 15 (2005) 233-246.
[28] Y. Xin and S. Zhao, Existence of periodic solution for generalized neutral Rayleigh equation with variable parameter, Advances in Difference Equation 2015 (2015) 209.
[29] G. L. Yang, J. Lu, A. C. J. Luo, On the computation of Lyapunov exponents for forced vibration of a Lennard-Jones oscillator, Chaos, Solitons and Fractals 23 (2005) 833-841.
[30] M. R. Zhang, Periodic solutions of linear and quasilinear neutral functional differential equations, Journal of Mathematical Analysis and Applications 189 (1995) 378-392.
[31] M. R. Zhang, Nonuniform nonresonance at the first eigenvalue of the p-Laplacian, Nonlinear Analysis 29 (1997) 41-51.
[32] M. R. Zhang, Periodic solutions of damped differential systems with repulsive singular forces, Proceedings of the American Mathematical Society 127 (1999) 401-407.


[^0]:    2010 Mathematics Subject Classification. 34B20, 34B24
    Keywords. Neutral functional differential equation, Positive periodic solutions, Continuation theorem, Time-varying delay, $p$ Laplacian, Singularity.

    Received: 25 August 2016; Accepted: 12 November 2017
    Communicated by Jelena Manojlović
    Research supported by the National Natural Science Foundation of China (Grant No. 11271197)
    Email addresses: fanchaokong88@sohu.com (Fanchao Kong), lushiping@sohu. com (Shiping Lu)

